

STUDY MATERIALS

VECTOR FIELDS

Mathematics Honours
Semester – 4
Paper – C9T Unit - 3

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• The significance of divergence (or, div) :-

Let us consider a typical vector field, water flow, and let it be denoted by $\bar{a}(\bar{x})$. It has magnitude equal to the mass of water crossing a unit area perpendicular to the direction of \bar{a} per unit time.

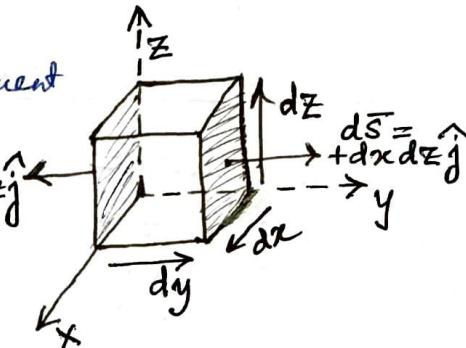
Let us take an infinitesimal volume element dV and calculate the balance of the flow of \bar{a} in and out of dV .

Let us consider the volume element $dV = dx dy dz$.

First, let us consider: $d\bar{s} = -dx dz \hat{j}$

the face of area $dx dz$
perpendicular to the y -axis
and facing outwards in

the (-ve) y -direction, i.e., $d\bar{s} = -dx dz \hat{j}$.



The component of the vector \bar{a} normal to $d\bar{s} (-dx dz \hat{j})$ is $\bar{a} \cdot \hat{j} = a_y$ (say), and is pointing inwards.
So the outward flux from this surface is

$$\bar{a} \cdot d\bar{s} = -a_y(x, y, z) dz dx \rightarrow ① \quad [\text{flux means mass/time}]$$

From the opposite face, i.e., $d\bar{s} = +dx dz \hat{j}$, the outward flux amount will be

$$a_y(x, y+dy, z) dz dx = (a_y + \frac{\partial a_y}{\partial y} dy) dz dx \quad [\text{by Taylor's theorem}] \rightarrow ②$$

∴ The total outward amount from these two faces is

$$-a_y dz dx + (a_y + \frac{\partial a_y}{\partial y} dy) dz dx$$

$$= \frac{\partial a_y}{\partial y} dx dy dz = \frac{\partial a_y}{\partial y} dv \rightarrow ③$$

Summing the other faces gives a total outward flux of $(\frac{\partial a_x}{\partial x} + \frac{\partial a_y}{\partial y} + \frac{\partial a_z}{\partial z}) dv = (\nabla \cdot \bar{a}) dv \rightarrow ④$

Therefore,

The divergence of a vector field represents the flux generation per unit volume at each point of the field.

Note: ① Divergence because it is an efflux not an influx.
② the total efflux from the infinitesimal volume is equal to the flux integrated over the surface of the volume.

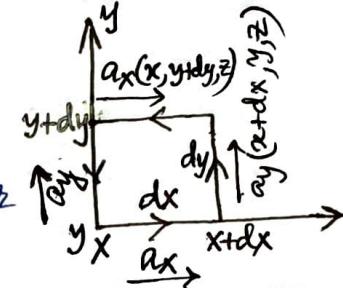
• The curl of a vector field

$$\nabla \times \vec{a} \equiv \text{curl}(\vec{a}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ a_x & a_y & a_z \end{vmatrix} = \sum i \left(\frac{\partial a_z}{\partial y} - \frac{\partial a_y}{\partial z} \right).$$

The circulation of a vector \vec{a} around any closed curve C is defined to be $\oint \vec{a} \cdot d\vec{r}$.

The curl of the vector field \vec{a} represents the Vorticity, or, circulation per unit area, of the field.

Let us consider the small rectangular element $dxdy$, and the circulation around the perimeter of a rectangular element.



The fields in the x -direction at the bottom & top are:

$$a_x(x, y, z) \quad \text{and} \quad a_x(x, y+dy, z) = a_x(x, y, z) + \frac{\partial a_x}{\partial y} dy. \quad \text{①}$$

And the fields in the y -direction at the left and right are:

$$a_y(x, y, z) \quad \text{and} \quad a_y(x+dx, y, z) = a_y(x, y, z) + \frac{\partial a_y}{\partial x} dx. \quad \text{②}$$

The total circulation dc starting from the bottom and working round in the anticlockwise sense, we have:

$$\begin{aligned} dc &= +[a_x dx] + [a_y(x+dx, y, z) dy] - [a_x(x, y+dy, z) dx] - [a_y dy] \\ &= [a_x dx] + [(a_y + \frac{\partial a_y}{\partial x} dx) dy] - [(a_x + \frac{\partial a_x}{\partial y} dy) dx] - [a_y dy] \\ &= \left(\frac{\partial a_y}{\partial x} - \frac{\partial a_x}{\partial y} \right) dx dy = (\nabla \times \vec{a}) \cdot d\vec{s}, \text{ where} \end{aligned}$$

$$d\vec{s} = dx dy \hat{k}.$$

Some Important definitions:

- ① A vector field with zero divergence is called Solenoidal.
- ② " " " " " " curl " " " irrotational.
- ③ " " Scalar " " " " " " gradient " " " constant.

74. Prove that $\nabla^2 r^n = n(n+1)r^{n-2}$, n is a constant.

$$\begin{aligned}
 \nabla^2 r^n &= \bar{\nabla} \cdot \bar{\nabla} r^n = \bar{\nabla} \cdot \left\{ \frac{d}{dr} (r^n) \bar{\nabla} r \right\} \\
 &= \bar{\nabla} \cdot \left(n r^{n-1} \frac{\bar{\nabla} r}{r} \right) = \bar{\nabla} \cdot (n r^{n-2} \bar{r}) \\
 &= \bar{\nabla} (n r^{n-2}) \cdot \bar{r} + n r^{n-2} (\bar{\nabla} \cdot \bar{r}) \\
 &= n \left\{ \frac{d}{dr} (r^{n-2}) \bar{\nabla} r \right\} \cdot \bar{r} + n r^{n-2} \bar{r} \\
 &= n(n-2) r^{n-3} \frac{\bar{r}}{r} \cdot \bar{r} + 3n r^{n-2} \\
 &= n(n-2) r^{n-4} (\bar{r} \cdot \bar{r}) + 3n r^{n-2} \\
 &= n(n-2) r^{n-4} r^2 + 3n r^{n-2} \\
 &= n(n-2) r^{n-2} + 3n r^{n-2} \\
 &= n r^{n-2} (n-2+3) = n(n+1) r^{n-2}. \\
 \therefore \nabla^2 r^n &= n(n+1) r^{n-2} \quad (\text{Proved})
 \end{aligned}$$

67. Find the constants a, b so that the surface $ax^2 - byz = (a+2)x$ will be orthogonal to the surface $4x^2y + z^3 = 4$ at the point $(1, -1, 2)$.

Let the surface $\phi_1(x, y, z) = ax^2 - byz - (a+2)x = 0$,

& " " " $\phi_2(x, y, z) = 4x^2y + z^3 - 4 = 0$.

Normal vector at $(1, -1, 2)$ to $\phi_1 = \bar{\nabla} \phi_1 \Big|_{(1, -1, 2)}$

and " " " " " to $\phi_2 = \bar{\nabla} \phi_2 \Big|_{(1, -1, 2)}$.

Now $\bar{\nabla} \phi_1 \Big|_{(1, -1, 2)} = (2ax - a - 2, -bz, -by) \Big|_{(1, -1, 2)}$

$$= (a-2, -2b, b)$$

$$\bar{\nabla} \phi_2 \Big|_{(1, -1, 2)} = (8xy, 4x^2, 3z^2) \Big|_{(1, -1, 2)} = (-8, 4, 12).$$

If $\phi_1 = 0, \phi_2 = 4$ be orthogonal, then

$$\bar{\nabla} \phi_1 \cdot \bar{\nabla} \phi_2 = 0 \Rightarrow (a-2)(-8) - 2b \cdot 4 + b \cdot 12 = 0$$

$$\Rightarrow -8a - 8b + 12b + 16 = 0$$

$$\Rightarrow 2a - b = 4 \longrightarrow \textcircled{1}.$$

Again the surface $\phi_1(x, y, z) = 0$ passes through the point $(1, -1, 2)$, i.e.,

$$a + 2b - (a+2) = 0 \Rightarrow 2b = 2 \Rightarrow b = 1 \rightarrow ②.$$

Using ② in ①, we obtain

$$2a = b + 4 = 1 + 4 \Rightarrow a = \frac{5}{2}.$$

⑥1 Find equations for the tangent plane and normal line to the surface $\mathcal{L} = x^2 + y^2$ at the point $(2, -1, 5)$.

Let the surface be $\phi(x, y, z) = x^2 + y^2 - z = 0$.

Normal vector \vec{N} to $\phi = 0$ at $(2, -1, 5)$ is

$$\vec{N} = \nabla \phi \Big|_{(2, -1, 5)} = (2x, 2y, -1) \Big|_{(2, -1, 5)} = (4, -2, -1).$$

Eqn of the tangent plane at $(2, -1, 5)$ is
 $(\vec{r} - \vec{r}_0) \cdot \vec{N} = 0$, where $\vec{r} = (x, y, z)$ is arbitrary point on the tangent plane, and $\vec{r}_0 = (2, -1, 5)$.

$$\Rightarrow \{(x, y, z) - (2, -1, 5)\} \cdot (4, -2, -1) = 0$$

$$\Rightarrow 4(x-2) - 2(y+1) - 1(z-5) = 0$$

$$\Rightarrow 4x - 2y - z = 8 + 2 - 5 = 5.$$

Eqn of the normal line at $(2, -1, 5)$ is
 $(\vec{r} - \vec{r}_0) \times \vec{N} = \vec{0}$, where $\vec{r} = (x, y, z)$ is any point on the normal line and $\vec{r}_0 = (2, -1, 5)$.

$$\Rightarrow (x-2, y+1, z-5) \times (4, -2, -1) = \vec{0}$$

$$\Rightarrow \frac{x-2}{4} = \frac{y+1}{-2} = \frac{z-5}{-1}. \text{ OR, } \underbrace{x=2+4t, y=-1-2t, z=5-t}_{(t \text{ is a parameter})}$$

Ex. If $\vec{\omega}$ is a constant vector and $\vec{v} = \vec{\omega} \times \vec{r}$, prove that $\operatorname{div} \vec{v} = 0$.

$$\operatorname{div} \vec{v} = \vec{v} \cdot (\vec{\omega} \times \vec{r}) = \vec{r} \cdot (\vec{v} \times \vec{\omega}) - \vec{\omega} \cdot (\vec{v} \times \vec{r})$$

$$= \vec{r} \cdot \vec{0} - \vec{\omega} \cdot \vec{0} = 0 - 0 = 0.$$

Ex. 105 If $f(r)$ is differentiable, prove that $f(r)\vec{r}$ is irrotational.

$$\begin{aligned}
 \bar{\nabla} \times \{f(r)\vec{r}\} &= \bar{\nabla} f(r) \times \vec{r} + f(r) \bar{\nabla} \times \vec{r} \quad [\because \bar{\nabla} \times (\phi \vec{A}) = \bar{\nabla} \phi \times \vec{A} + \phi (\bar{\nabla} \times \vec{A})] \\
 &= \{f'(r) \bar{\nabla} r\} \times \vec{r} + f(r) \vec{0} \quad [\because \bar{\nabla} f(u) = f'(u) \bar{\nabla} u] \\
 &= \left\{ f'(r) \frac{\vec{r}}{r} \right\} \times \vec{r} + \vec{0} \quad [\because \bar{\nabla} r = \sum i \frac{\partial r}{\partial x} = \sum i \frac{x}{r} = \frac{\vec{r}}{r}] \\
 &= \frac{f'(r)}{r} (\vec{r} \times \vec{r}) + \vec{0} \\
 &= \frac{f'(r)}{r} \vec{0} + \vec{0} \\
 &= \vec{0} + \vec{0} \\
 \therefore f(r)\vec{r} &\stackrel{?}{=} \vec{0}
 \end{aligned}$$

$\therefore f(r)\vec{r}$ is irrotational. Proved.

Maitry R
2nd year

(16) Find the angle of intersection at the point $(2, -1, 2)$ of the surfaces $x^2 + y^2 + z^2 = 9$ and $z = x^2 + y^2 - 3$.

The angle of intersection of the given surfaces is equal to the angle of intersection of their normals.

Let $\phi_1(x, y, z) = x^2 + y^2 + z^2 - 9 = 0 \rightarrow ①$

& $\phi_2(x, y, z) = x^2 + y^2 - z - 3 = 0 \rightarrow ②$,

$$\bar{\nabla} \phi_1 \Big|_{(2, -1, 2)} = (2x, 2y, 2z) \Big|_{(2, -1, 2)} = (4, -2, 4) \rightarrow \text{Normal to } \phi_1$$

$$\bar{\nabla} \phi_2 \Big|_{(2, -1, 2)} = (2x, 2y, -1) \Big|_{(2, -1, 2)} = (4, -2, -1) \rightarrow \text{Normal to } \phi_2$$

\therefore Angle between their normals at $(2, -1, 2)$ is given

by $\cos \theta = \frac{\bar{\nabla} \phi_1 \cdot \bar{\nabla} \phi_2}{|\bar{\nabla} \phi_1| |\bar{\nabla} \phi_2|} = \frac{16 + 4 - 4}{\sqrt{36} \cdot \sqrt{21}} = \frac{16}{6\sqrt{21}} = \frac{8}{3\sqrt{21}}$.

$\therefore \theta = \cos^{-1} \left(\frac{8}{3\sqrt{21}} \right)$, which is the required angle.

Ex: 83

① Prove $\nabla^2 f(r) = \frac{d^2 f}{dr^2} + \frac{2}{r} \frac{df}{dr}$. ② Find $f(r)$ s.t. $\nabla^2 f(r) = 0$.

$$\begin{aligned}
\nabla^2 f(r) &= \bar{\nabla} \cdot \bar{\nabla} f(r) = \bar{\nabla} \cdot f'(r) \bar{\nabla} r \quad [\because \nabla f(u) = f'(u) \bar{\nabla} u] \\
&= \bar{\nabla} \cdot \frac{f'(r)}{r} \bar{\nabla} \quad [\because \bar{\nabla} r = \frac{\bar{x}}{r}] \\
&= \frac{f'(r)}{r} \bar{\nabla} \cdot \bar{\nabla} + \bar{\nabla} \cdot \bar{\nabla} \frac{f'(r)}{r} \quad [\because \bar{\nabla}(fF) = f(\bar{\nabla} F) + F \cdot (\bar{\nabla} f)] \\
&= \frac{3f'(r)}{r} + \bar{\nabla} \cdot \left\{ -\frac{f'(r)}{r^2} + \frac{f''(r)}{r} \right\} \bar{\nabla} r \\
&= \frac{3f'(r)}{r} + \bar{r} \cdot \left\{ \frac{f''(r)}{r} - \frac{f'(r)}{r^2} \right\} \frac{\bar{x}}{r} \\
&= \frac{3f'(r)}{r} + \left\{ \frac{f''(r)}{r^2} - \frac{f'(r)}{r^3} \right\} (\bar{r}, \bar{r}) \\
&= \frac{3f'(r)}{r} + \left\{ \frac{f''(r)}{r^2} - \frac{f'(r)}{r^3} \right\} r^2 = \frac{3f'(r)}{r} + f''(r) - \frac{f'(r)}{r} \\
\therefore \nabla^2 f(r) &= f''(r) + \frac{2}{r} f'(r) = \frac{d^2 f}{dr^2} + \frac{2}{r} \frac{df}{dr}.
\end{aligned}$$

For $\nabla^2 f(r) = \frac{d^2 f}{dr^2} + \frac{2}{r} \frac{df}{dr} = 0 \rightarrow ①$

we substitute $z = \log r$. Then $\frac{dz}{dr} = \frac{1}{r}$.

Now $\frac{df}{dr} = \frac{df}{dz} \cdot \frac{dz}{dr} = \frac{1}{r} \frac{df}{dz} \Rightarrow$

a, $\frac{d^2 f}{dr^2} = \frac{d}{dr} \left(\frac{1}{r} \frac{df}{dz} \right) = -\frac{1}{r^2} \frac{df}{dz} + \frac{1}{r} \frac{d^2 f}{dz^2} \cdot \frac{dz}{dr}$
 $= -\frac{1}{r^2} \frac{df}{dz} + \frac{1}{r^2} \frac{d^2 f}{dz^2} = \frac{1}{r^2} \left(\frac{d^2 f}{dz^2} - \frac{df}{dz} \right).$

From ①, we get,

$$\frac{1}{r^2} \left(\frac{d^2 f}{dz^2} - \frac{df}{dz} \right) + \frac{2}{r} \cdot \frac{1}{r} \frac{df}{dz} = 0$$

a, $\frac{d^2 f}{dz^2} + \frac{df}{dz} = 0 \Rightarrow \frac{\frac{d^2 f}{dz^2}}{\frac{df}{dz}} = -1$

Integrating both sides w.r.t. z, we get

$$\log \left(\frac{df}{dz} \right) = -z + \log C, \text{ or, } \frac{df}{dz} = C \cdot e^{-z}$$

Again integrating w.r.t. z, we get

$$f = -C e^{-z} + D; \text{ a, } f(r) = D - \frac{C}{r}; \text{ where } C \text{ & } D \text{ are arbitrary constants.}$$

102. Show that $\bar{A} = (6xy + z^3)\hat{i} + (3x^2 - z)\hat{j} + (3xz^2 - y)\hat{k}$ is irrotational. Find ϕ s.t. $\bar{A} = \nabla\phi$.

$$\text{curl } \bar{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 6xy + z^3 & 3x^2 - z & 3xz^2 - y \end{vmatrix} = \hat{i}(-1+1) + \hat{j}(3z^2 - 3z^2) + \hat{k}(6x - 6x) = \hat{i}0 + \hat{j}0 + \hat{k}0 = \bar{0}$$

$\therefore \bar{A}$ is irrotational.

$$\text{Now } \bar{A} = \nabla\phi$$

$$\Rightarrow \nabla\phi \cdot d\bar{r} = \bar{A} \cdot d\bar{r}$$

$$\begin{aligned} \Rightarrow d\phi &= (6xy + z^3)dx + (3x^2 - z)dy + (3xz^2 - y)dz \\ &= (6xy dx + 3x^2 dy) + (z^3 dx + 3xz^2 dz) \\ &\quad - (z dy + y dz) \\ &= d(3x^2 y) + d(xz^3) - d(yz). \end{aligned}$$

$$\therefore d\phi = d(3x^2 y + xz^3 - yz)$$

Integrating $\Rightarrow \underline{\phi = 3x^2 y + xz^3 - yz + C}.$
(C is a constant).

86. Find the most general differentiable function $f(r)$ so that $f(r)\bar{r}$ is solenoidal.

$$f(r)\bar{r} \text{ is solenoidal} \Rightarrow \nabla \cdot (f(r)\bar{r}) = 0$$

$$\Rightarrow \nabla f(r) \cdot \bar{r} + f(r) \nabla \cdot \bar{r} = 0$$

$$\Rightarrow f'(r) \bar{r} \cdot \bar{r} + 3f(r) = 0$$

$$\Rightarrow f'(r) \frac{\bar{r}}{r} \cdot \bar{r} + 3f(r) = 0$$

$$\Rightarrow \frac{f'(r)}{r} r^2 + 3f(r) = 0$$

$$\Rightarrow rf'(r) + 3f(r) = 0 \Rightarrow \frac{f'(r)}{f(r)} + \frac{3}{r} = 0$$

Integrating w.r.t. r , $\int \frac{f'(r)}{f(r)} dr + \int \frac{3}{r} dr = 0$

$$\Rightarrow \log f(r) + 3 \log r = \log C \Rightarrow r^3 f(r) = C.$$

$$\therefore f(r) = C/r^3, (C \text{ is a constant})$$

103. Show that $\bar{E} = \bar{r}/r^2$ is irrotational. Find ϕ such that $\bar{E} = -\nabla\phi$ and such that $\phi(a) = 0$ for $a > 0$.

$$\begin{aligned}\text{Ans: } \bar{\nabla} \times \bar{E} &= \bar{\nabla} \times \frac{\bar{r}}{r^2} = \bar{\nabla}\left(\frac{1}{r^2}\right) \times \bar{r} + \frac{1}{r^2}(\bar{\nabla} \times \bar{r}) \\ &= \frac{d}{dr}\left(\frac{1}{r^2}\right)\bar{r}r - \frac{1}{r^2}\bar{0} = -\frac{2}{r^3}\bar{r} \times \bar{r} \\ &= -\frac{2}{r^4}(\bar{r} \times \bar{r}) = \bar{0}\end{aligned}$$

$\therefore \bar{E}$ is irrotational.

$$\text{To find } \phi: \quad \bar{E} = -\bar{\nabla}\phi$$

$$\Rightarrow \frac{\bar{r}}{r^2} = -\bar{\nabla}\phi$$

$$\Rightarrow \bar{\nabla}\phi \cdot d\bar{r} = -\frac{\bar{r}}{r^2} \cdot d\bar{r}$$

$$\Rightarrow \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz = -\frac{1}{r^2}(x dx + y dy + z dz)$$

$$\Rightarrow d\phi = -\frac{1}{r^2} \cdot \frac{1}{2} d(x^2 + y^2 + z^2)$$

$$\Rightarrow d\phi = -\frac{1}{2} \frac{d(r^2)}{r^2}$$

$$\text{Integrating} \Rightarrow \phi = -\frac{1}{2} \log r^2 + \text{Constant}$$

$$\Rightarrow \phi(r) = -\log r + \text{Constant.}$$

$$\text{Now } \phi(a) = 0 \text{ for } a > 0$$

$$\therefore \phi(a) = 0 = -\log a + \text{constant}$$

$$\Rightarrow \text{constant} = \log a.$$

$$\therefore \phi = -\log r + \log a = \log(a/r).$$

$$\therefore \phi = \underline{\log(a/r)}. \quad (\text{Ans})$$

Ex. (106) @ Is there a differentiable vector function \bar{V} such that $\operatorname{curl} \bar{V} = \bar{r}$?

Let $\operatorname{curl} \bar{V} = \bar{r}$, then $\bar{\nabla} \cdot (\bar{\nabla} \times \bar{V}) = \bar{\nabla} \cdot \bar{r}$

$$\text{Now, L.H.S.} = \bar{\nabla} \cdot (\bar{\nabla} \times \bar{V}) = \bar{\nabla} \cdot \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_1 & V_2 & V_3 \end{vmatrix} \quad [\text{Let } \bar{V} = (V_1, V_2, V_3)]$$

$$= \bar{\nabla} \cdot \left\{ \left(\frac{\partial V_3}{\partial y} - \frac{\partial V_2}{\partial z} \right) \hat{i} + \left(\frac{\partial V_1}{\partial z} - \frac{\partial V_3}{\partial x} \right) \hat{j} + \left(\frac{\partial V_2}{\partial x} - \frac{\partial V_1}{\partial y} \right) \hat{k} \right\}$$

$$= \frac{\partial}{\partial x} \left(\frac{\partial V_3}{\partial y} - \frac{\partial V_2}{\partial z} \right) + \frac{\partial}{\partial y} \left(\frac{\partial V_1}{\partial z} - \frac{\partial V_3}{\partial x} \right) + \frac{\partial}{\partial z} \left(\frac{\partial V_2}{\partial x} - \frac{\partial V_1}{\partial y} \right)$$

$$= \frac{\partial^2 V_3}{\partial x \partial y} - \frac{\partial^2 V_2}{\partial x \partial z} + \frac{\partial^2 V_1}{\partial y \partial z} - \frac{\partial^2 V_3}{\partial y \partial x} + \frac{\partial^2 V_2}{\partial z \partial x} - \frac{\partial^2 V_1}{\partial z \partial y}$$

$$\text{R.H.S.} = \bar{\nabla} \cdot \bar{r} = \frac{\partial}{\partial x}(x) + \frac{\partial}{\partial y}(y) + \frac{\partial}{\partial z}(z) = 1+1+1=3.$$

$$\therefore \text{L.H.S.} = 0 \neq 3 = \text{R.H.S.}$$

\therefore There is no differentiable vector function \bar{V} s.t. $\operatorname{curl} \bar{V} = \bar{r}$.

Ex. (92) For what value of the constant a will the vector $\bar{A} = (axy - z^3) \hat{i} + (a-2)x^2 \hat{j} + (1-a)xz^2 \hat{k}$ have its curl identically equal to zero?

$$\bar{\nabla} \times \bar{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (axy - z^3) & (a-2)x^2 & (1-a)xz^2 \end{vmatrix} = 0 \hat{i} + [-3z^2 - (1-a)z^2] \hat{j} + [2x(a-2) - ax] \hat{k}$$

$$= (-4z^2 + az^2) \hat{j} + (xa - 4x) \hat{k}$$

$$= z^2(a-4) \hat{j} + x(a-4) \hat{k}$$

$$\text{Now } \bar{\nabla} \times \bar{A} = \bar{0}$$

$$\Rightarrow z^2(a-4) \hat{j} + x(a-4) \hat{k} = 0 \hat{i} + 0 \hat{j} + 0 \hat{k}.$$

$$\Rightarrow a-4=0 \Rightarrow \underline{a=4}. \quad (\text{Ans.})$$

Ques. Is there a differentiable vector function \bar{V} such that $\operatorname{curl} \bar{V} = 2\hat{i} + \hat{j} + 3\hat{k}$? If so, find \bar{V} .

Ans: We have, $\bar{\nabla} \cdot \operatorname{curl} \bar{V} = \bar{\nabla} \cdot (2\hat{i} + \hat{j} + 3\hat{k})$
 $\Rightarrow 0 = 0$; Equality holds.

\therefore Yes, \exists a vector function \bar{V} s.t.
 $\operatorname{curl} \bar{V} = 2\hat{i} + \hat{j} + 3\hat{k}$.

To find \bar{V} :

We have, $\bar{\nabla} \cdot \operatorname{curl} \bar{V} = 0 \rightarrow ①$

and $\operatorname{curl} \bar{V} = 2\hat{i} + \hat{j} + 3\hat{k} = \bar{a}$ (say) $\rightarrow ②$.

With view of ①, ② has all the solutions given by $\bar{V} = \bar{V}_0 + \bar{\nabla} \phi$, where \bar{V}_0 is any vector function and $\phi(x, y, z)$ is an arbitrary scalar function.

Now $\operatorname{curl} \bar{V} = \operatorname{curl} (\bar{V}_0 + \bar{\nabla} \phi) = \operatorname{curl} \bar{V}_0 + \operatorname{curl} \bar{\nabla} \phi$
 $\Rightarrow \bar{a} = \operatorname{curl} \bar{V}_0 + \bar{0} = \operatorname{curl} \bar{V}_0$.

$\therefore \operatorname{curl} \bar{V}_0 = \bar{a} \rightarrow ④$.

Since \bar{V}_0 is arbitrary, let us take

$$\bar{V}_0 = (0, V_2, V_3) \rightarrow ⑤$$

Then $\operatorname{curl} \bar{V}_0 = \bar{a} \Rightarrow \left(\frac{\partial V_3}{\partial y} - \frac{\partial V_2}{\partial z}, \frac{\partial V_3}{\partial x}, \frac{\partial V_2}{\partial x} \right) = (2, 1, 3)$

$$\Rightarrow \frac{\partial V_3}{\partial y} - \frac{\partial V_2}{\partial z} = 2; -\frac{\partial V_3}{\partial x} = 1; \frac{\partial V_2}{\partial x} = 3. \rightarrow ⑥$$

Now integrating $-\frac{\partial V_3}{\partial x} = 1$ partially w.r.t. x , we get

$$V_3 = -x + f(y, z) \rightarrow ⑦ \quad " \quad " \quad " \quad "$$

Also integrating $\frac{\partial V_2}{\partial x} = 3$ " " " functions.

Let us choose $f(y, z) = 0$ in ⑦, then we get

$$V_2 = 3x. \text{ Then from } ⑥, \frac{\partial V_3}{\partial y} - \frac{\partial V_2}{\partial z} = 2 \Rightarrow \frac{\partial f}{\partial y} - 0 = 2$$

Integrating partially w.r.t. y ; $f = 2y + h(z)$; choosing $h(z) = 0$.

$$\therefore \bar{V}_0 = (0, 3x, -x + 2y)$$

$$\therefore \bar{V} = \bar{V}_0 + \bar{\nabla} \phi = 3x\hat{i} + (2y - x)\hat{j} + 2y\hat{k} + \bar{\nabla} \phi. \text{ (Ans).}$$