## 2.12. Equation of motion of Matter Waves.

(i) Time-independent. Schroedinger equation. The non-dissipation of the wave-packet of the material particle has been explained by assuming the necessity of the guiding wave obeying Schroedinger wave equation which we shall derive here.

Consider a system of stationary waves to be associated with the particle, Let (x, y, z) be the co-ordinates of the particle and  $\psi$  the wave displacement for the de Broglie waves at any time t. Then the differential equation of the wave motion in three dimensions can be written in classical way as

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} = \frac{1}{u^2} \frac{\partial^2 \psi}{\partial t^2}, \qquad \dots (1)$$

where u is the wave velocity.

The solution of equation (1) gives  $\psi$  as a periodic displacement in terms of time, i.e.,

 $\psi(x, y, z, t) = \psi_0(x, y, z) e^{-i\omega t},$  ...(2)

where  $\psi_0$  is the amplitude at the point considered. It is function of (x, y, z), i.e., the position r and not of time t, where

$$r=ix+jy+kz$$
.

The equation (2) may be expressed as

$$\psi(\mathbf{r}, t) = \psi_0(\mathbf{r}) e^{-i\omega t}. \qquad ...(3)$$

Differentiating equation (3) twice with respect to t, we get

$$\frac{\partial^2 \psi}{\partial t^2} = -\omega^2 \psi_0 (\mathbf{r}) e^{-i\omega t}$$
$$= -\omega^2 \psi.$$

Substituting this in equation (1), we get

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} = -\frac{\omega^2}{u^2} \psi. \tag{4}$$

But

$$=\frac{2\pi u}{\lambda},$$

i.e.

Also

$$\frac{\omega}{u} = \frac{2\pi}{\lambda}.$$

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} = \nabla^2 \psi,$$
...(6)

∇² being Laplacian operator.

Using (5) and (6) equation (4) becomes

$$\nabla^2 \psi + \frac{4\pi^2}{\lambda^2} \psi = 0. \tag{7}$$

So far we have not introduced wave mechanical concept and so the treatment is general. For introducing the concept of wave mechanics we must put from de Broglie equation

$$\lambda = \frac{h}{mv}.$$
 (8)

Substituting this in equation (7), we get

$$\nabla^2 \psi + \frac{4\pi^2 m^2 v^2}{h^2} \psi = 0. \tag{9}$$

If E and V are the total and potential energies of the particle respectively, then its kinetic energy  $\frac{1}{2}mv^2$  is given by

 $\frac{1}{2}mv^2 = E - V,$  $m^2v^2 = 2m (E - V).$ 

which gives

Substituting this in equation (9), we get

$$\nabla^2 \psi + \frac{8\pi^2 m}{h^2} (E - V) \psi = 0 \qquad ...(10)$$

The above equation is called Schroedinger time independent wave equation. The quantity  $\psi$  is usually referred as wave function.

Let us now substitute in equation (10),

$$\hbar = \frac{h}{2\pi}.$$
 ...(11)

Then the Schroedinger time-independent wave equation, in usually used form, may be written as

$$\nabla^2 \psi + \frac{2m}{\hbar^2} (E - V) \psi = 0.$$
 ...(12)

(ii) Schroedinger equation for a free particle. For a free particle V=0; therefore if we put V=0 in equation (12), it will become the Schroedinger equation for a free particle, i.e.,

$$\nabla^2 \psi + \frac{2mE}{\hbar^2} \psi = 0. \tag{13}$$

(iii) Time-dependent Schroedinger Equation.

Time-dependent Schroedinger equation may be obtained by eliminating E from equation (12).

Differentiating equation (3), with respect to t, we get

$$\frac{\partial \psi}{\partial t} = -i\omega\psi_{0}(\mathbf{r}) e^{-i\omega t}$$

$$= -i (2\pi\nu) \psi_{0}(\mathbf{r}) e^{-i\omega t} \qquad \text{(since } \omega = 2\pi\nu)$$

$$= -2\pi i \nu \psi \qquad \text{using (3)}$$

$$= -\frac{2\pi i E}{h} \phi \qquad \left(\text{since } E = h\nu, i.e. } \nu = \frac{E}{h}\right)$$

$$= -\frac{iE}{h} \psi \times \frac{i}{i} \qquad \text{using (11)}$$

which gives

$$E\psi = i \, \hbar \, \frac{\partial \psi}{\partial t} \, . \tag{14}$$

Substituting value of E4 from above equation in (12), we get

or 
$$\nabla^2 \psi + \frac{2m}{\hbar^2} \left[ i \hbar \frac{\partial \psi}{\partial t} - V \psi \right] = 0$$
or 
$$\nabla^2 \psi = -\frac{2m}{\hbar^2} \left[ i \hbar \frac{\partial \psi}{\partial t} - V \psi \right]$$
i.e. 
$$-\frac{\hbar^2}{2m} \nabla^2 \psi + V \psi = i \hbar \frac{\partial \psi}{\partial t}. \qquad ...(15)$$

This equation contains the time and hence is called time dependent Schroedinger equation.

Equation (15) may be written as

$$\left(-\frac{\hbar^2}{2m}\,\nabla^2 + V\right) \psi = i\,\hbar\,\frac{\partial\psi}{\partial t}. \qquad ...(16)$$

The operator  $\left(\frac{\hbar^2}{2m}\nabla^2+V\right)$  is called Hamiltonian and is

represented by H; while operator  $i\hbar\partial/\partial t$  operating on  $\psi$ , gives E which may be seen from (14). Thus equation (16) may be written as  $H\psi=E\psi$ . ...(17)

The above forms of the Schroedinger's equation describe the motion of a non-relativistic material particle.

Normalised & Orthogonal Wave functions: We know that 44x du or 147 du represents the probability of binding the portice in the rolm slement do. In physical problem we come across the situations where the positive is loound by boroce to a limited region. For examples! the election in a atom, the particle in a loop with impenebable walks. In such the total probability of finding the particle in the ontire space is a course, lenity, i.e, 1/4(x,t) du 21 where integration extends over all apace. Equation () may be worthen as (4(x,t) (x (x,t) du=1 A wave function a high atalifies above equation is said to be normalized to unity. when two particle is bound to the limited regions the postuleigh of finding the particle of infinity distance is zero, in the af x = 0 Any notation of the wave equation may be nomalized by multiplying ar dividing by a complant and it can readily seen that Sunday 21 the result is also a solution of the move function. It fi & fi are two different wave functions, both being otalis-factory solutions of wave equation for a given cystem, then these functions will be normalised to 14.4. du=1 & 14.4. du=1 It the two wave-functions Piss 4; are mesh that the integral

fif, do = 0 or fy, 4; du = 0, it then the want functions are naidts be mutually orthogonal. Stationary State Solutions! is independent of time, tuen the state of the system is raid to be otationary at de a system in the state represented by the wave function  $\frac{f(x,y,z,t)}{n=1} = \sum_{n=1}^{\infty} a_n \varphi_n(x,y,z) e^{-iEnt/\hbar} - 0$ the He conjugate is represented by  $\varphi^*(n, y, t, t) = 20 \sum_{m=1}^{\infty} \alpha_m^m \varphi_m^*(n, y, t) e^{i \times mt/n}$ nother yyt = [ = an dn (mio, 2) e-iEn/h ] [ = am qin (a, ore) Zanan & (2, y, 2) (2, (x, y, 2) + I I anam on (midit) on (midit) of (midit) ei (Em-En) +/+ where the prime on the souble nummation indicates that the terms with m = n are excluded. clearly time enters in the probability function upper, hence of expressed by equation of is not a stationary state notation. 4 pr will be independent of time to only if an's are zero for all values except for one value of En. In neah a case the wavefunction will contain only animale form & will be represented by 4(m, v, t, t) = on (x, 4,2) 5 int/ --- 0 The notution represented by equation (2) is stationary state solution, since 44 = 9 9 9 , which is independent of time.

2.17. Expectation Values of Dynamical Quantities.

According to Born the wave-function  $\psi$  has probabilistic interpretation, therefore it is essential to calculate the average or expectation value of any dynamical quantity defined by the wave-function. In physics such dynamical quantities are space-co-ordinates, momenta and energy of the system.

The average or expectation value of a dynamical quantity is the mechanical expectation for the result of a single measurement.

It may be defined as the average of the result af a large number of measurements on independent systems.

The expectation value of any quantity f(r) which depends upon position, for normalised wave-function may be written as

$$\langle f(\mathbf{r}) \rangle = \int P(\mathbf{r}, t) f(\mathbf{r}) d\tau$$

$$= \int \psi^* (\mathbf{r}, t) f(\mathbf{r}) \psi (\mathbf{r}, t) d\tau. \qquad ...(1)$$

This is equivalent to the following three expressions:

$$\langle x \rangle = \int \psi^* x \psi d\tau$$

$$\langle y \rangle = \int \psi^* y \psi d\tau$$

$$\langle z \rangle = \int \psi^* z \psi d\tau$$
...(3)

where  $\langle x \rangle$ ,  $\langle y \rangle$  and  $\langle z \rangle$  are the expectation values of the co-ordinates x, y and z of the particle respectively.

The expectation value of the potential energy, which is also the function of position, is written as

$$\langle V \rangle = \int V(\mathbf{r}, t) P(\mathbf{r}, t) d\tau$$

$$= \int \psi^*(\mathbf{r}, t) V(\mathbf{r}, t) \psi(\mathbf{r}, t) d\tau. \qquad ...(4)$$

So far we have only considered the expectation values of the quantities which depend upon position and no other quantities which are of dynamical interest, such as momentum and energy. The expectation value of these quantities may be found by using the corresponding differential operator.

One form of Schroedinger's equation is

$$i\hbar \frac{\partial \psi}{\partial t} = E\psi,$$

so that the total energy can be represented by differential operator that acts on the wave-function  $\psi$ , i.e.

$$E=i\hbar \frac{\partial}{\partial t}$$
 ...(5)

we have

total energy=kinetic energy+potential energy

i.e.

$$E = \frac{p^2}{2m} + V,$$

$$\langle E \rangle = \langle \frac{p^2}{2m} \rangle + \langle V \rangle. \qquad \dots (6)$$

so that

Also we have from eqn. (16) and (17) of section 2.2.

$$E=-\frac{\hbar^2}{2m} \nabla^2+V,$$

so that

$$\langle E \rangle = \langle -\frac{\hbar^2}{2m} \nabla^2 \rangle + \langle V \rangle.$$
 ...(7)

Comparing (6) and (7), we get

$$p^2 = -\hbar^2 \nabla^2 = \frac{\hbar^2}{i^2} \nabla^2$$

so that

$$\mathbf{p} = \frac{\hbar}{i} \nabla = -i\hbar \nabla. \qquad ...(8)$$

This eqn. suggests that the momentum can be represented by differential operator  $(-i\hbar \nabla)$ .

We can, now, write the expectation values of momentum and energy using the corresponding operators. The average value of energy, using eqn. (5), is written as

$$\langle E \rangle = \int \psi^* i \hbar \frac{\partial \psi}{\partial t} d\tau = i \hbar \int \psi^* \frac{\partial \psi}{\partial t} d\tau. \qquad ...(9)$$

The average or expectation value of momentum, using eqn. (8) is written as

$$\langle \mathbf{p} \rangle = \int \psi^* (-i\hbar \nabla) \psi \, d\tau$$

$$= -i\hbar \int \psi^* \nabla \psi \, d\tau. \qquad \dots (10)$$

This equation is equivalent to three component equations given by

$$\langle p_x \rangle = -i\hbar \int \psi^* \frac{\partial \psi}{\partial x} d\tau,$$

$$\langle p_y \rangle = -i\hbar \int \psi^* \frac{\partial \psi}{\partial y} d\tau,$$

$$\langle p_z \rangle = -i\hbar \int \psi^* \frac{\partial \psi}{\partial z} d\tau,$$
...(11)

and

where  $\langle p_x \rangle$ ,  $\langle p_y \rangle$ ,  $\langle p_z \rangle$  are the expectation values of the components of the momentum along X, Y and Z axes respectively.

It is to noted that the above formulae of expection values only hold if the wave-function  $\psi$  is properly normalised: otherwise we have the definition of expectation value of any quantity f to be

$$\langle f \rangle = \frac{\int \psi^* f \psi \, d\tau}{\int \psi^* \psi \, d\tau} \qquad \dots (12)$$

Therefore if the wave function is not normalised we have to use the definition given by eqn. (12) and the equations (1), (2), (3), (4), (9) and (11) will be modified accordingly.

Moreover if the expectation values are to defined using operators, the integrand will consist of the operator operating on  $\psi$ ; multiplied on the left by  $\psi^*$ .