

UG CBCS 2ND Sem.

Subject: Mathematics (Hons.)

Paper: C4T. / Unit-IV.

Name of the teacher:

Dr. Sangita Chakraborty

Associate Professor

Deptt. of Mathematics

Kharagpur College

WhatsApp No. 9434455417

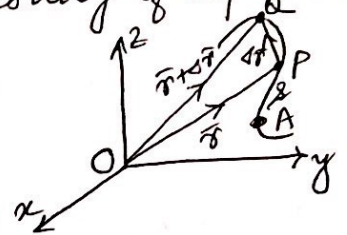
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Vector Calculus.

Differential geometry involves a study of space curves and space surfaces.

Let $\vec{r} = \vec{f}(s)$ be a space curve.

Unit tangent vector: $\hat{t} = \frac{d\vec{r}}{ds}$.



Unit Principal normal: Since $\hat{t} \cdot \hat{t} = 1$, hence

$$\frac{d}{ds}(\hat{t} \cdot \hat{t}) = 0 \Rightarrow 2\hat{t} \cdot \frac{d\hat{t}}{ds} = 0 \Rightarrow \hat{t} \cdot \frac{d\hat{t}}{ds} = 0$$

i.e., $\frac{d\hat{t}}{ds}$, if not zero, must be perpendicular to $\hat{t}$.

If $\hat{n}$ is a unit vector in the direction of $\frac{d\hat{t}}{ds}$, then $\frac{d\hat{t}}{ds}$ is parallel to $\hat{n}$, i.e., $\frac{d\hat{t}}{ds} = \kappa \hat{n}$, $\kappa (\geq 0)$ is said to be the curvature of the curve at P.

$\hat{n}$ is called unit principal normal.

Unit Binormal: Let $\hat{b} = \hat{t} \times \hat{n}$ such that $\hat{t}, \hat{n}, \hat{b}$ form a right-handed system of orthogonal unit vectors. A directed line through the point P in the direction of $\hat{b}$ is called binormal to the curve.

Tangent Vector at P = $\frac{d\vec{r}}{dt}$ [If $\vec{r} = \vec{f}(t)$ be the space curve]

Unit tangent vector at P = $\frac{d\vec{r}}{ds} \equiv \hat{t} = \frac{\frac{d\vec{r}}{dt}}{|\frac{d\vec{r}}{dt}|}$

Principal Normal at P = $\frac{d\hat{t}}{ds}$

Unit Principal Normal at P = $\frac{\frac{d\hat{t}}{ds}}{|\frac{d\hat{t}}{ds}|} = \frac{d\hat{t}}{ds} = \hat{n}$.

Unit Binormal at P = $\hat{b} = \hat{t} \times \hat{n}$.

Eqn. of the tangent line at P = $(\vec{R} - \vec{r}) \times \frac{d\vec{r}}{ds} = \vec{0}$

" " " normal " at P = $(\vec{R} - \vec{r}) \times \hat{n} = \vec{0}$

" " " binormal " at P = $(\vec{R} - \vec{r}) \times \hat{b} = \vec{0}$

where $\vec{R}$ is the current vector on the respective lines.

Osculating Plane: Containing $\hat{t}$ and $\hat{n}$.

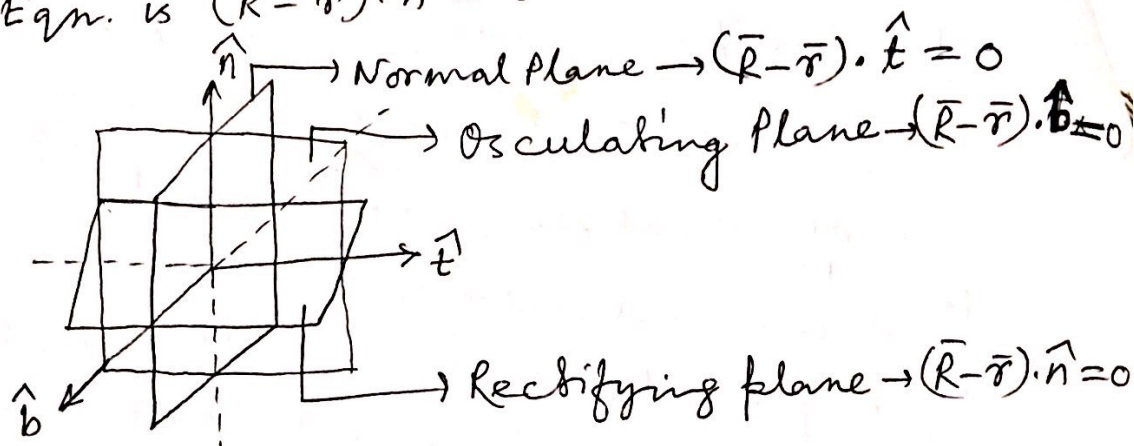
$\therefore$ Eqn is $(\bar{R}-\bar{r}) \cdot \hat{b} = 0$

Normal Plane: Containing $\hat{n}$ and $\hat{b}$.

Eqn is $(\bar{R}-\bar{r}) \cdot \hat{t} = 0$.

Rectifying Plane: Containing $\hat{t}$ and $\hat{b}$.

Eqn. is $(\bar{R}-\bar{r}) \cdot \hat{n} = 0$



Prove the Frenet-Serret formulae:

(i) $\frac{d\hat{t}}{ds} = \kappa \hat{n}$, (ii) $\frac{d\hat{b}}{ds} = -\tau \hat{n}$, (iii) $\frac{d\hat{n}}{ds} = \tau \hat{b} - \kappa \hat{t}$.

Proof: (i) Since $\hat{t} \cdot \hat{t} = 1 \Rightarrow \frac{d}{ds}(\hat{t} \cdot \hat{t}) = 0 \Rightarrow \hat{t} \cdot \frac{d\hat{t}}{ds} = 0$
 $\Rightarrow \frac{d\hat{t}}{ds}$ is $\perp^r$ to $\hat{t}$.

If $\hat{n}$ is a unit vector in the direction $\frac{d\hat{t}}{ds}$, then
 $\frac{d\hat{t}}{ds} = \kappa \hat{n}$, κ is the curvature, $\rho = 1/\kappa$, radius of curvature.

(ii) Let $\hat{b} = \hat{t} \times \hat{n}$, so that $\frac{d\hat{b}}{ds} = \hat{t} \times \frac{d\hat{n}}{ds} + \frac{d\hat{t}}{ds} \times \hat{n}$
 $= \hat{t} \times \frac{d\hat{n}}{ds} + \kappa \hat{n} \times \hat{n}$
 $\therefore \frac{d\hat{b}}{ds} = \hat{t} \times \frac{d\hat{n}}{ds}$

Ex Now, $\hat{t} \cdot \frac{d\hat{b}}{ds} = \hat{t} \cdot \hat{t} \times \frac{d\hat{n}}{ds} = 0 \Rightarrow \hat{t}$ is $\perp^r$ to $\frac{d\hat{b}}{ds}$.

Again from $\hat{b} \cdot \hat{b} = 1$, we have $\hat{b} \cdot \frac{d\hat{b}}{ds} = 0$.

$\Rightarrow \frac{d\hat{b}}{ds}$ is $\perp^r$ to $\hat{b}$ and thus in the plane of $\hat{t}$ and $\hat{n}$. Also $\frac{d\hat{b}}{ds}$ is $\perp^r$ to $\hat{t}$, then it must be $\parallel$ to $\hat{n}$. Then $\frac{d\hat{b}}{ds} = \tau \hat{n}$, τ the torsion
 $\sigma = 1/\tau$, the radius of torsion

Ex

1) Since $\hat{t}, \hat{n}, \hat{b}$ form a right-handed system, so do $\hat{n}, \hat{b}, \hat{t}$, i.e., $\hat{n} = \hat{b} \times \hat{t}$.
Then $\frac{d\hat{n}}{ds} = \hat{b} \times \frac{d\hat{t}}{ds} + \frac{d\hat{b}}{ds} \times \hat{t} = \hat{b} \times \kappa \hat{n} - \tau \hat{n} \times \hat{t} = -\kappa \hat{t} + \tau \hat{b}$ from.

Let the parametric eqn of the space curve be given as:
 $\vec{r} = \vec{r}(t)$, where $x = x(t), y = y(t), z = z(t)$

Differentiating w.r.t. t , we get

$$\dot{\vec{r}} = \frac{d\vec{r}}{dt} = \frac{d\vec{r}}{ds} \cdot \frac{ds}{dt} = \hat{t} \dot{s} \rightarrow (2)$$

It follows, that $|\dot{\vec{r}}| = |\dot{s}| \rightarrow (3)$

Again, differentiating (2) w.r.t. t ~~to (2)~~, we obtain,

$$\ddot{\vec{r}} = \frac{d\dot{\vec{r}}}{dt} \dot{s} + \hat{t} \ddot{s} = \frac{d\hat{t}}{ds} \dot{s}^2 + \hat{t} \ddot{s} = \kappa \hat{n} \dot{s}^2 + \hat{t} \ddot{s} \rightarrow (4)$$

And finally differentiating (4) w.r.t. t , we get

$$\begin{aligned} \ddot{\vec{r}} &= \dot{\kappa} \hat{n} \dot{s}^2 + \kappa \frac{d\hat{n}}{ds} \dot{s}^3 + 2\kappa \hat{n} \dot{s} \ddot{s} + \frac{d\hat{t}}{ds} \dot{s} \ddot{s} + \hat{t} \ddot{\ddot{s}} \\ &= \dot{\kappa} \hat{n} \dot{s}^2 + \kappa (\tau \hat{b} - \kappa \hat{t}) \dot{s}^3 + 2\kappa \hat{n} \dot{s} \ddot{s} + \kappa \hat{n} \dot{s} \ddot{s} + \hat{t} \ddot{\ddot{s}} \\ &= \ddot{\ddot{s}} \hat{t} + \cancel{\ddot{\ddot{s}} \hat{t}} (2\dot{s} \ddot{s} \kappa + \dot{\kappa} \dot{s}^2) \hat{n} + \dot{s}^3 \kappa (\tau \hat{b} - \kappa \hat{t}) \\ &= (\ddot{\ddot{s}} - \dot{s}^3 \kappa^2) \hat{t} + (3\dot{s} \ddot{s} \kappa + \dot{s}^2 \dot{\kappa}) \hat{n} + \dot{s}^3 \kappa \tau \hat{b} \rightarrow (5) \end{aligned}$$

Hence, we obtain,

$$\dot{\vec{r}} \times \ddot{\vec{r}} = \kappa \dot{s}^3 \hat{b} \rightarrow (6) \Rightarrow \kappa = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{\dot{s}^3} = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3}$$

$$\text{and } \dot{\vec{r}} \times \ddot{\vec{r}} \cdot \ddot{\vec{r}} = [\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}] = \kappa^2 \dot{s}^6 \tau \rightarrow (7) \Rightarrow \tau = \frac{[\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}]}{|\dot{\vec{r}} \times \ddot{\vec{r}}|^2}$$

Eqn. of Osculating plane: $(\vec{r} - \vec{r}) \cdot \dot{\vec{r}} \times \ddot{\vec{r}} = 0$

" " Normal plane: $(\vec{r} - \vec{r}) \cdot \ddot{\vec{r}} = 0$

" " Rectifying plane: $(\vec{r} - \vec{r}) \cdot (\dot{\vec{r}} \times \ddot{\vec{r}}) \times \ddot{\vec{r}} = 0$

For a plane curve: $x = x(t), y = y(t)$

$$\vec{r} = x\hat{i} + y\hat{j}, \quad \dot{\vec{r}} = \dot{x}\hat{i} + \dot{y}\hat{j}, \quad \ddot{\vec{r}} = \ddot{x}\hat{i} + \ddot{y}\hat{j}$$

$$\kappa = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3} = \frac{|\dot{x}\ddot{y} - \dot{y}\ddot{x}|}{(\dot{x}^2 + \dot{y}^2)^{3/2}}, \quad \tau = 0.$$

In particular, if the curve has the Cartesian eqn $y = f(x)$, we take $x = t, y = f(t)$ as parametric form. $\therefore \kappa = \frac{|\ddot{y}|}{(1 + \dot{y}^2)^{3/2}}$

Three fundamental planes associated with every ordinary point (P) of a smooth curve are:

(i) Osculating plane $\rightarrow$ A plane containing the tangent and principal normal at P.

(ii) Normal Plane $\rightarrow$ A plane containing principal normal and the binormal at P.

(ii) Normal Plane $\rightarrow$ A plane containing the tangent and the binormal at P .
(iii) Rectifying plane $\rightarrow$ A plane containing the tangent and the binormal at P .
The normal plane is perpendicular to the binormal. The rectifying plane is perpendicular to the normal.

These 3 planes are mutually perpendicular.

These 3 planes are mutually perpendicular.

If $\vec{r}$ be the p.v. of any point on the plane and $\vec{r}_0$ be the p.v. of the specified point of the smooth curve, then

Equation of plane: $(\vec{r} - \vec{r}_0) \cdot \hat{b} = 0 \rightarrow (1)$

The equation of osculating plane: $(\vec{r} - \vec{r}_0) \cdot \hat{b} = 0 \rightarrow (1)$
 The equation of normal: $(\vec{r} - \vec{r}_0) \cdot \hat{t} = 0 \rightarrow (2)$

The equation of Osculating plane : $(\vec{r} - \vec{r}_0) \cdot \hat{t} = 0 \rightarrow (2)$
 " " " Normal " : $(\vec{r} - \vec{r}_0) \cdot \hat{n} = 0 \rightarrow (3)$

" " Normal " : $(\bar{r} - \bar{r}_0) \cdot \hat{n} = 0 \rightarrow \textcircled{3}$
 " " Rectifying " : $(\bar{r} - \bar{r}_0) \cdot \hat{n} = 0 \rightarrow \textcircled{3}$
 " " " : $(\bar{r} - \bar{r}_0) \cdot \hat{n} = 0 \rightarrow \textcircled{3}$

Find the expressions for curvature (κ) and torsion (τ) of the curve whose vector equation is given by

$$\bar{r} = \bar{r}(t) \rightarrow \textcircled{1}$$

of the curve where $\vec{r} = \vec{r}(t) \rightarrow ①$, $\dot{\vec{r}} = \vec{r}' \dot{s} = \hat{t} \dot{s} \rightarrow ②$, $|\dot{\vec{r}}| = |\dot{s}| \rightarrow ③$, where $\dot{\vec{r}} = \frac{d\vec{r}}{dt}$, $\vec{r}' = \frac{d\vec{r}}{ds}$.

$$\ddot{\vec{r}} = \frac{d\hat{t}}{dt} \dot{s} + \hat{t} \ddot{s} = \frac{d\hat{t}}{ds} \dot{s}^2 + \hat{t} \ddot{s} = \kappa \hat{n} \dot{s}^2 + \hat{t} \ddot{s}$$
$$\therefore \frac{d^2}{dt^2} = \kappa \dot{\theta}^2 \hat{n} + \ddot{\theta} \hat{k} \longrightarrow (4)$$
$$\begin{aligned} \ddot{\vec{r}} &= \dot{\kappa} \dot{s}^2 \hat{n} + \dot{s} \ddot{\kappa} \hat{t} \longrightarrow (4) \\ \ddot{\vec{r}} &= \dot{\kappa} \dot{s}^2 \hat{n} + 2\dot{\kappa} \dot{s} \dot{s} \hat{n} + \kappa \dot{s}^3 \frac{d\hat{n}}{ds} + \ddot{s} \hat{t} + \dot{s} \dot{s} \frac{d\hat{t}}{ds} \end{aligned}$$
$$\ddot{\vec{r}} = \dot{\kappa} \dot{s}^2 \hat{n} + 2\kappa \dot{s} \ddot{s} \hat{n} + \kappa \dot{s}^3 \left(\frac{d\hat{n}}{ds} - \kappa \hat{t} \right) + \ddot{s} \hat{t} + \dot{s}' \dot{s} \kappa \hat{n}$$
$$= \dot{\kappa} \dot{s}^2 \hat{n} + 2\kappa \dot{s} \ddot{s} \hat{n} + \kappa \dot{s}^3 (\tau \hat{b} - \kappa \hat{t}) + \ddot{s} \hat{t} + \dot{s}' \dot{s} \kappa \hat{n} \longrightarrow (S)$$
$$\therefore \ddot{\vec{r}} = (\ddot{s} - \kappa^2 \dot{s}^3) \hat{t} + (3\kappa \dot{s} \ddot{s} + \dot{\kappa} \dot{s}^2) \hat{n} + \kappa \tau \dot{s}^3 \hat{b}$$

Now $\ddot{\vec{r}} \times \ddot{\vec{r}} = K \hat{b} \rightarrow \textcircled{6}$

Now $\ddot{\overline{p}} \times \ddot{\overline{p}} = K^2 p^6$
and $\ddot{\overline{p}} \times \ddot{\overline{p}}, \ddot{\overline{p}} = K^2 p^8 \rightarrow \textcircled{7}$

$$\therefore K = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3} = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3} \rightarrow (8)$$
$$\text{and } \tau = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}} \cdot \ddot{\vec{r}}|}{k^2 \dot{s}^6} = \frac{[\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}]}{|\dot{\vec{r}} \times \ddot{\vec{r}}|^2} \rightarrow (9)$$

Note:

Therefore equations ①, ②, ③ of 3 fundamental planes
 $\vec{r} = \vec{r}_0 + \vec{u} \cdot \vec{u}_1 + \vec{v} \cdot \vec{u}_2 \rightarrow$ osculating plane

Therefore equations (1), (2), (3) become:

$$(\vec{r} - \vec{r}_0) \cdot \dot{\vec{r}} \times \ddot{\vec{r}} = 0 \rightarrow \text{Osculating plane}$$

$$(\vec{r} - \vec{r}_0) \cdot \ddot{\vec{r}} = 0 \rightarrow \text{Normal Plane}$$

$(\vec{r} - \vec{r}_0) \cdot \vec{r} = 0 \rightarrow$ Normal Plane
 $(\vec{r} - \vec{r}_0) \cdot \frac{d\vec{r}}{dt} = 0 \rightarrow$ Rectifying Plane

$$(\vec{r} - \vec{r}_0) \cdot (\dot{\vec{r}} \times \ddot{\vec{r}}) = 0 \rightarrow \text{Rectifying plane.}$$

■ Prove the relations: $\kappa = |\vec{r}''|$, $\vec{r}' \times \vec{r}'' = \kappa \hat{b}$, $[\vec{r}' \vec{r}'' \vec{r}'''] = \kappa^2 \tau$, $\vec{r}''' = \kappa(\tau \hat{b} - \kappa \hat{t}) + \kappa' \hat{n}$; for the space curve $\vec{r} = \vec{r}(s)$, s being the arc-length of the point (P) from some fixed point of the curve.

$$\vec{r}' = \frac{d\vec{r}}{ds} = \hat{t}, \quad \vec{r}'' = \frac{d\hat{t}}{ds} = \kappa \hat{n} \Rightarrow \kappa = |\vec{r}''|.$$

$$\text{Now } \vec{r}' \times \vec{r}'' = \hat{t} \times \kappa \hat{n} = \kappa \hat{b}$$

$$\text{Also } \vec{r}''' = \kappa' \hat{n} + \kappa \frac{d\hat{n}}{ds} = \kappa(\tau \hat{b} - \kappa \hat{t}) + \kappa' \hat{n}.$$

$$\vec{r}' \times \vec{r}'' \cdot \vec{r}''' = \kappa^2 \tau \Rightarrow [\vec{r}' \vec{r}'' \vec{r}'''] = \kappa^2 \tau.$$

$$\therefore \kappa = |\vec{r}''|, \quad \tau = \frac{[\vec{r}' \vec{r}'' \vec{r}''']}{|\vec{r}''|^2}, \quad \rho = \frac{1}{\kappa} \rightarrow \text{radius of curvature}$$

$$\sigma = \frac{1}{\tau} \rightarrow \text{torsion}$$

■ For a plane curve: $x = x(t)$, $y = y(t)$, obtain κ and τ .

$$\vec{r} = x\hat{i} + y\hat{j}; \quad \dot{\vec{r}} = \dot{x}\hat{i} + \dot{y}\hat{j}; \quad \ddot{\vec{r}} = \ddot{x}\hat{i} + \ddot{y}\hat{j}; \quad |\dot{\vec{r}} \times \ddot{\vec{r}}| = |\dot{x}\ddot{y} - \ddot{x}\dot{y}|$$

$$\kappa = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3} = \frac{|\dot{x}\ddot{y} - \ddot{x}\dot{y}|}{(\dot{x}^2 + \dot{y}^2)^{3/2}}$$

$$\ddot{\vec{r}} = \ddot{x}\hat{i} + \ddot{y}\hat{j}, \quad \dot{\vec{r}} \times \ddot{\vec{r}} \cdot \ddot{\vec{r}} = (\dot{x}\ddot{y} - \ddot{x}\dot{y})\hat{k} \cdot (\ddot{x}\hat{i} + \ddot{y}\hat{j}) = 0$$

$$\therefore \tau = \frac{[\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}]}{|\dot{\vec{r}} \times \ddot{\vec{r}}|^2} = 0$$

In particular, if $y = f(x)$; $\left. \begin{matrix} x = t \\ y = f(t) \end{matrix} \right\}$, then

$$\kappa = \frac{|\ddot{y}|}{(1 + \dot{y}^2)^{3/2}}$$

Equation of the tangent line: $(\vec{r} - \vec{r}_0) \times \dot{\vec{r}} = \vec{0}$, (at $\vec{r}_0$).
or, $(\vec{r} - \vec{r}_0) \times \hat{t} = \vec{0}$, (at $\vec{r}_0$).

Equation of the normal plane: $(\vec{r} - \vec{r}_0) \cdot \dot{\vec{r}} = 0$ (at $\vec{r}_0$).

Ex 53. Show that the Frenet-Serret formulae can be written in the form $\frac{d\hat{t}}{ds} = \bar{\omega} \times \hat{t}$, $\frac{d\hat{n}}{ds} = \bar{\omega} \times \hat{n}$, $\frac{d\hat{b}}{ds} = \bar{\omega} \times \hat{b}$ and determine $\bar{\omega}$.

Frenet-Serret formulae:

$$\frac{d\hat{t}}{ds} = \kappa \hat{n} \rightarrow ①, \quad \frac{d\hat{n}}{ds} = \tau \hat{b} - \kappa \hat{t} \rightarrow ②, \quad \frac{d\hat{b}}{ds} = -\tau \hat{n}.$$

From ②, $\frac{d\hat{n}}{ds} = \tau \hat{b} - \kappa \hat{t} = \tau(\hat{t} \times \hat{n}) + \kappa(\hat{b} \times \hat{n}) = (\tau \hat{t} + \kappa \hat{b}) \times \hat{n}$
 $= \bar{\omega} \times \hat{n}$, where $\bar{\omega} = \tau \hat{t} + \kappa \hat{b}$.

From ①, $\frac{d\hat{t}}{ds} = \kappa \hat{n} = \kappa(\hat{b} \times \hat{t}) = (\kappa \hat{b} + \tau \hat{t}) \times \hat{t}$ [$\because \hat{t} \times \hat{t} = \vec{0}$]
 $= \bar{\omega} \times \hat{t}$, where $\bar{\omega} = \tau \hat{t} + \kappa \hat{b}$.

From ③, $\frac{d\hat{b}}{ds} = -\tau \hat{n} = \tau(\hat{t} \times \hat{b}) = (\tau \hat{t} + \kappa \hat{b}) \times \hat{b}$ [$\because \hat{b} \times \hat{b} = \vec{0}$]
 $= \bar{\omega} \times \hat{b}$.

$$\therefore \bar{\omega} = \tau \hat{t} + \kappa \hat{b}.$$

Ex. 66. A particle moves along a space curve $\vec{r} = \vec{r}(t)$ with velocity $\vec{v}$. Show that its accelⁿ $\vec{a}$ is given by $\vec{a} = \frac{dv}{dt} \hat{t} + \frac{v^2}{\rho} \hat{n}$. ρ is the radius of curvature.

Let $\vec{r}$ be the p.v. of the particle at any time t .

$$\therefore \vec{v} = \frac{d\vec{r}}{dt} = \frac{d\vec{r}}{ds} \frac{ds}{dt} = \hat{t} v$$

$$\begin{aligned} \vec{a} &= \frac{d(\vec{v})}{dt} = \frac{d}{dt}(\hat{t} v) = \frac{d\hat{t}}{dt} v + \hat{t} \frac{dv}{dt} \\ &= \hat{t} \frac{dv}{dt} + \frac{d\hat{t}}{ds} \frac{ds}{dt} v = \hat{t} \frac{dv}{dt} + v^2 \kappa \hat{n} \\ &= \hat{t} \frac{dv}{dt} + \frac{v^2}{\rho} \hat{n}. \end{aligned}$$

Ex. 66. A particle moves along the curve $\vec{r} = (t^3 - 4t) \hat{i} + (t^2 + 4t) \hat{j} + (8t^2 - 3t^3) \hat{k}$, t is the time. Find the magnitudes of the tangential and normal components of its accelⁿ when $t = 2$.

$$\vec{a} = \hat{t} \frac{dv}{dt} + \frac{v^2}{\rho} \hat{n}. \quad \begin{array}{ll} \text{tangential component} &= \frac{dv}{dt} \\ \text{normal} &= \frac{v^2}{\rho}. \end{array}$$

$$\vec{v} = \frac{d\vec{r}}{dt} = (3t^2 - 4) \hat{i} + (2t + 4) \hat{j} + (16t - 9t^2) \hat{k}.$$

$$v = |\vec{v}| = \sqrt{(3t^2 - 4)^2 + (2t + 4)^2 + (16t - 9t^2)^2}^{1/2} = 12, \text{ at } t = 2,$$

$$\begin{aligned} \frac{dv}{dt} &= \frac{1}{2v} \left\{ 2(3t^2 - 4) \times 6t + 2(2t + 4) \times 2 + 2(16t - 9t^2) \times (16 - 18t) \right\} \\ &= \frac{1}{2 \times 12} \{ 24 \times 8 + 4 \times 8 + 2 \times (-4) \times (-20) \} = \frac{4 \times 8 \times 12}{2 \times 12} = 16 \end{aligned}$$

$$\text{Now } \rho = \frac{|\dot{\vec{r}}|^3}{|\dot{\vec{r}} \times \ddot{\vec{r}}|} = \frac{v^3}{|\dot{\vec{r}} \times \ddot{\vec{r}}|}$$

$$\therefore \frac{v^2}{\rho} = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{v}$$

$$\text{Now } \dot{\vec{r}} = (3t^2 - 4, 2t + 4, 16t - 9t^2) = (8, 8, -4) \text{ at } t=2$$

$$\ddot{\vec{r}} = (6t, 2, 16 - 18t) = (12, 2, -20) \text{ at } t=2.$$

$$\therefore \dot{\vec{r}} \times \ddot{\vec{r}} = (-152, 112, -80) = 8(-19, 14, -10)$$

$$\therefore |\dot{\vec{r}} \times \ddot{\vec{r}}| = 8\sqrt{19^2 + 14^2 + 10^2} = 8\sqrt{361 + 196 + 100} = 8\sqrt{657}$$

$$\therefore \frac{v^2}{\rho} = \frac{8\sqrt{657}}{\frac{12}{3}} = \frac{2 \times 8\sqrt{73}}{3} = \frac{16\sqrt{73}}{3}$$

69. Prove that the acceleration vector of a particle moving along a space curve always lies in the osculating plane.

$$\text{We have } \vec{a} = \frac{dv}{dt} \hat{t} + \frac{v^2}{\rho} \hat{n}$$

$$\therefore \vec{a} \cdot \hat{t} \times \hat{n} = \frac{dv}{dt} \hat{t} \cdot \hat{t} \times \hat{n} + \frac{v^2}{\rho} \hat{n} \cdot \hat{t} \times \hat{n}$$

$= 0$
 $\therefore \vec{a}, \hat{t}, \hat{n}$ lie on the same plane
 i.e., $\vec{a}$ lies in the plane containing $\hat{t}$ & $\hat{n}$,
 called the osculating plane.

64. Find equations for the tangent plane & normal line to the surface $4z = x^2 - y^2$ at $(3, 1, 2)$.

$$\text{Let } \phi(x, y, z) = x^2 - y^2 - 4z = 0$$

$$\text{Let } x = u, y = v, z = \frac{u^2 - v^2}{4}; \quad u=3, v=1$$

$$\therefore \vec{r} = \vec{r}(u, v) = u\hat{i} + v\hat{j} + \frac{u^2 - v^2}{4}\hat{k}$$

$$\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} = (\hat{i} + \frac{u}{2}\hat{k}) \times (\hat{j} - \frac{v}{2}\hat{k}) = \hat{k} + \frac{u}{2}(-\hat{i}) + \frac{v}{2}\hat{j}$$

$$= (-\frac{u}{2}, \frac{v}{2}, 1) = (-\frac{3}{2}, \frac{1}{2}, 1) \text{ at } (3, 1, 2)$$

$$\vec{n} = (-\frac{3}{2}, \frac{1}{2}, 1)$$

$$\text{Eqn of tangent plane: } (x-3)(-\frac{3}{2}) + (y-1)\frac{1}{2} + (z-2)1 = 0$$

$$\therefore -3x + y + 2z + 4 = 0$$

Space curves

Parametric eqns of a space curve:

$$x = x(t), y = y(t), z = z(t), \quad a \leq t \leq b.$$

Vector form of a space curve:

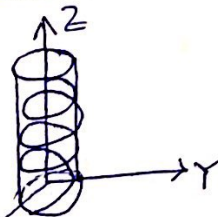
$$\vec{r} = \vec{r}(t) \equiv \vec{f}(t)$$

① Circular helix:- The parametric eqns.

$x = a \cos t, y = a \sin t, z = bt$ ($b \neq 0$).
represent a curve on the surface of a circular cylinder and cutting the generators at a constant angle. This curve is known as a circular helix.

This curve is twisted, i.e., does not lie in a plane.

This curve is described by a moving point P which is subjected to a constant rotation together with a translation in the direction of the axis of rotation.



Verify for circular helix, $\kappa = \frac{a}{a^2+b^2}, \tau = \frac{b}{a^2+b^2}$.

$$x = a \cos t, y = a \sin t, z = bt.$$

$$\kappa = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3}, \quad \tau = \frac{[\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}]}{|\dot{\vec{r}} \times \ddot{\vec{r}}|^2}$$

$$\begin{aligned} \vec{r}(t) &= x\hat{i} + y\hat{j} + z\hat{k} = a \cos t \hat{i} + a \sin t \hat{j} + bt \hat{k} \\ \dot{\vec{r}} &= -a \sin t \hat{i} + a \cos t \hat{j} + b \hat{k} \\ \ddot{\vec{r}} &= -a \cos t \hat{i} - a \sin t \hat{j} \\ \ddot{\vec{r}} &= a \sin t \hat{i} - a \cos t \hat{j} \end{aligned}$$

$$\kappa = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3} = \frac{\sqrt{a^2(a^2+b^2)}}{(a^2+b^2)^{3/2}}$$

$$\kappa = \frac{a}{a^2+b^2}$$

$$\tau = \frac{[\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}]}{|\dot{\vec{r}} \times \ddot{\vec{r}}|^2} = \frac{a^2 b}{a^2(a^2+b^2)} = \frac{b}{a^2+b^2}$$

$$\begin{aligned} \dot{\vec{r}} \times \ddot{\vec{r}} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -a \sin t & a \cos t & b \\ -a \cos t & -a \sin t & 0 \end{vmatrix} \\ &= a^2 \sin^2 t \hat{k} + a^2 \cos^2 t \hat{k} - ab \sin t \hat{j} + ab \sin t \hat{j} \\ &= a^2 \hat{k} \\ |\dot{\vec{r}} \times \ddot{\vec{r}}|^2 &= a^4 \\ |\dot{\vec{r}}|^2 &= a^2 + b^2 \\ [\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}] &= \dot{\vec{r}} \cdot (\ddot{\vec{r}} \times \ddot{\vec{r}}) = 0 \end{aligned}$$

Also find the length of the curve measured from $t=0$ to some point t is $t\sqrt{a^2+b^2}$.

We have $\dot{\vec{r}} = \frac{d\vec{r}}{dt} = \frac{d\vec{r}}{ds} \cdot \frac{ds}{dt} = \hat{t} \frac{ds}{dt} \Rightarrow |\dot{\vec{r}}| = \left| \frac{ds}{dt} \right|$

$$\therefore \left| \frac{ds}{dt} \right| = \sqrt{a^2+b^2} \Rightarrow \int ds = \int_0^t \sqrt{a^2+b^2} dt \Rightarrow s = t\sqrt{a^2+b^2}$$

Ex: If the tangent to a curve makes a constant angle α with a fixed line, then $\kappa = \pm \tau \tan \alpha$, and conversely show that if κ/τ is constant the tangent makes a constant angle with a fixed direction.

Let $\hat{e}$ be the unit vector parallel to the fixed line. So that by the given condition.

$\hat{t} \cdot \hat{e} = \cos \alpha \rightarrow (1)$
Differentiating w.r.t. s (arc-length), we get

$$\frac{d\hat{t}}{ds} \cdot \hat{e} = 0 \rightarrow (2) \quad [\text{Since the direction of } \hat{e} \text{ is fixed}]$$

By Frenet-Serret's formula, we have

$$\kappa \hat{n} \cdot \hat{e} = 0 \quad [\text{using (2) \& } \frac{d\hat{t}}{ds} = \kappa \hat{n}]$$

$$\hat{n} \cdot \hat{e} = 0 \Rightarrow \hat{n} \text{ is } \perp \text{ to } \hat{e}$$

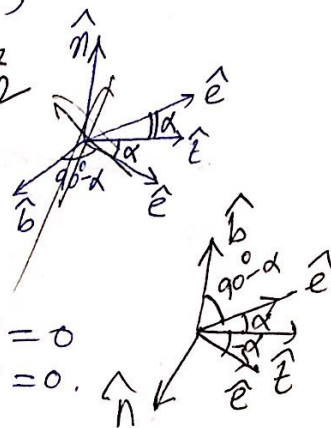
and since $\hat{n} = \hat{b} \times \hat{t}$, & $\hat{n}$ is $\perp$ to $\hat{e}$, therefore $\hat{b}, \hat{t}, \hat{e}$ are coplanar.

$$\text{So that } \hat{b} \cdot \hat{e} = \cos(90^\circ \pm \alpha) = \pm \sin \alpha$$

$$\hat{n} \cdot \hat{e} = 0, \text{ differentiating w.r.t. } s,$$

$$\frac{d\hat{n}}{ds} \cdot \hat{e} = 0$$

$$\begin{aligned} \Rightarrow (\tau \hat{b} - \kappa \hat{t}) \cdot \hat{e} &= 0 \Rightarrow \tau \hat{b} \cdot \hat{e} - \kappa \hat{t} \cdot \hat{e} = 0 \\ &\Rightarrow \tau (\pm \sin \alpha) - \kappa \cos \alpha = 0 \\ &\Rightarrow \kappa = \pm \tau \tan \alpha. \end{aligned}$$



Conversely, let $\kappa = c\tau$, where c is some scalar constant

$$\text{Now, } \frac{d\hat{t}}{ds} = \kappa \hat{n} = \left(-\frac{\kappa}{\tau}\right) \frac{d\hat{b}}{ds} = (-c) \frac{d\hat{b}}{ds}$$

Integrating we get, $\hat{t} = -c\hat{b} + \vec{d}$, where $\vec{d}$ is constant vector of integration,

$$\text{Now, } \hat{t} \cdot \hat{t} = \hat{t} \cdot (-c\hat{b} + \vec{d}) = c(\hat{t} \cdot \hat{b}) + \hat{t} \cdot \vec{d}$$

$$\Rightarrow 1 = c \cdot 0 + \hat{t} \cdot \vec{d} \Rightarrow \hat{t} \cdot \vec{d} = 1$$

Hence the tangent makes a constant angle with the direction of the fixed vector $\vec{d}$.

Proved

Ex: Prove that a necessary and sufficient condition that a curve, $\vec{r} = \vec{r}(s)$ be a helix is that $\vec{r}'' \cdot \vec{r}''' \times \vec{r}'''' = 0$.

Soln: $\vec{r} = \vec{r}(s) \rightarrow (1)$

$\therefore \vec{r}' = \frac{d\vec{r}}{ds} = \hat{t} \rightarrow (2)$

Now, $\frac{d\hat{t}}{ds} = \frac{d^2\vec{r}}{ds^2} = \vec{r}'' = \kappa \hat{n}$, [by Frenet-Serret's formula]

$\vec{r}''' = \frac{d\kappa}{ds} \hat{n} + \kappa \frac{d\hat{n}}{ds} = \frac{d\kappa}{ds} \hat{n} + \kappa (\tau \hat{b} - \kappa \hat{t}) \rightarrow (3)$

$\vec{r}'''' = \frac{d^2\kappa}{ds^2} \hat{n} + \frac{d\kappa}{ds} \frac{d\hat{n}}{ds} + \kappa \tau \frac{d\hat{b}}{ds} + \frac{d\kappa}{ds} \tau \hat{b} + \kappa \frac{d\tau}{ds} \hat{b} - 2\kappa \frac{d\kappa}{ds} \hat{t}$
 $= \frac{d^2\kappa}{ds^2} \hat{n} + \frac{d\kappa}{ds} (\tau \hat{b} - \kappa \hat{t}) + \kappa \tau (-\tau \hat{n}) + \frac{d\kappa}{ds} \tau \hat{b} + \kappa \frac{d\tau}{ds} \hat{b}$
 $= -3\hat{t} \kappa \frac{d\kappa}{ds} + \left(\frac{d^2\kappa}{ds^2} - \kappa^3 - \kappa \tau^2 \right) \hat{n} + \left(\tau \frac{d\kappa}{ds} + \kappa \frac{d\tau}{ds} \right) \hat{b}$

$\therefore \vec{r}'' \times \vec{r}'''' = +3\kappa \left(\frac{d\kappa}{ds} \right)^2 \hat{b} + \left[2\tau \left(\frac{d\kappa}{ds} \right)^2 + \kappa \frac{d\kappa}{ds} \frac{d\tau}{ds} \right] \hat{t}$
 $+3\kappa^2 \tau \frac{d\kappa}{ds} \hat{n} - \left(\kappa \tau \frac{d^2\kappa}{ds^2} - \kappa^4 \tau - \kappa^2 \tau^3 \right) \hat{t}$
 $- \left(\kappa^2 \tau \frac{d\kappa}{ds} + \kappa^5 - \kappa^3 \tau^2 \right) \hat{b} + \kappa^2 \left(2\tau \frac{d\kappa}{ds} + \kappa \frac{d\tau}{ds} \right) \hat{n}$

$\therefore \vec{r}'' \cdot \vec{r}''' \times \vec{r}'''' = -3\kappa^3 \tau \frac{d\kappa}{ds} + 2\kappa^3 \tau \frac{d\kappa}{ds} + \kappa^4 \frac{d\tau}{ds}$
 $= \left(-\tau \frac{d\kappa}{ds} + \kappa \frac{d\tau}{ds} \right) \kappa^3 = 0$

$\therefore \frac{\kappa}{\tau} = \frac{d\kappa/ds}{d\tau/ds} = \frac{d\kappa}{d\tau}$

$\therefore \frac{d(\frac{\kappa}{\tau})}{d(\frac{\kappa}{\tau})} = 0 \Rightarrow \log\left(\frac{\kappa}{\tau}\right) = \log C$
 $\Rightarrow \frac{\kappa}{\tau} = \text{Constant}$

$\therefore$ If, $\vec{r}'' \cdot \vec{r}''' \times \vec{r}'''' = 0$, then $\frac{\kappa}{\tau} = \text{Constant} \Rightarrow \vec{r} = \vec{r}(s)$ be a helix.

Now, if $\frac{\kappa}{\tau} = \text{Constant}$, then $\frac{d}{ds}\left(\frac{\kappa}{\tau}\right) = 0$

$\therefore \tau \frac{d\kappa}{ds} - \kappa \frac{d\tau}{ds} = 0$

$\therefore \tau \frac{d\kappa}{ds} - \kappa \frac{d\tau}{ds} = 0$

$\therefore \vec{r}'' \cdot \vec{r}''' \times \vec{r}'''' = \left(-\tau \frac{d\kappa}{ds} + \kappa \frac{d\tau}{ds} \right) \kappa^3 = 0$

Ex: The displacement vector $\vec{r}$ at any time t of a moving point is

$$\vec{r} = \vec{a} \cos \omega t + \vec{b} \sin \omega t,$$

where $\vec{a}$ and $\vec{b}$ are constant vectors and ω is a scalar constant.

- (a) Find the velocity $\vec{v}$ and show that $\vec{r} \times \vec{v} =$ a constant vector.
(b) Show that the acceleration is directed towards the origin and is proportional to the displacement.
(c) What is the physical interpretation of this motion?

Soln: (a) $\vec{r} = \vec{a} \cos \omega t + \vec{b} \sin \omega t$.

$$\vec{v} = \frac{d\vec{r}}{dt} = (-\vec{a} \sin \omega t + \vec{b} \cos \omega t) \omega$$

$$\begin{aligned} \vec{r} \times \vec{v} &= (\vec{a} \cos \omega t + \vec{b} \sin \omega t) \times (-\vec{a} \sin \omega t + \vec{b} \cos \omega t) \omega \\ &= \omega (\vec{a} \times \vec{b}) \{ \cos^2 \omega t + \sin^2 \omega t \} \end{aligned}$$

$$\vec{r} \times \vec{v} = \omega (\vec{a} \times \vec{b}) \rightarrow \text{a constant vector.}$$

$$(b) \vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2\vec{r}}{dt^2} = \omega^2 (-\vec{a} \cos \omega t - \vec{b} \sin \omega t) = -\omega^2 \vec{r}$$

acceleration $\vec{a}$ is opposite to the direction of $\vec{r}$.
i.e., $\vec{a}$ is directed towards the origin.
and $\vec{a} \propto \vec{r}$

(c) Physical interpretation:

The motion is that of a particle moving on the circumference of a circle with constant angular speed ω . The force, directed towards the centre of the circle is the centrifugal force.

2) Show that the acceleration $\vec{a}$ of a particle which travels along a space curve with vel. $\vec{v}$ is given by $\vec{a} = \frac{dv}{dt} \hat{t} + \frac{v^2}{\rho} \hat{n}$, where $\hat{t}$ is the unit tangent vector to the space curve, $\hat{n}$ is its unit principal normal, ρ is the radius of curvature, $\rho = \frac{v^3}{|\vec{v} \times \vec{a}|}$

Mechanics :- A particle moves along the curve $\vec{r} = (t^3 - 4t)\hat{i} + (t^2 + 4t)\hat{j} + (8t^2 - 3t^3)\hat{k}$, where t is the time. Find the magnitudes of the tangential and normal components of its acceleration when $t = 2$.

Solution : Velocity $\vec{v} = v\hat{t}$, $v = |\vec{v}|$. Differentiating w.r.t. t , we get,

$$\vec{a} = \frac{d\vec{v}}{dt} = \frac{d}{dt}(v\hat{t}) = \frac{dv}{dt}\hat{t} + v\frac{d\hat{t}}{ds} \cdot \frac{ds}{dt} = \frac{dv}{dt}\hat{t} + v^2 \cdot \frac{1}{\rho} \hat{n}$$

∴ $\vec{a} = \frac{dv}{dt} \hat{t} + \frac{v^2}{\rho} \hat{n}$. Magnitude of the tangential component of its acceleration

$$= \left| \frac{dv}{dt} \right| \text{ or } \text{normal} \quad \text{Now, } \frac{1}{\rho} = \frac{|\vec{v} \times \vec{a}|}{v^3} = \frac{|\vec{v} \times \frac{dv}{dt}\hat{t} + v^2 \hat{n}|}{v^3} = \frac{v^2}{\rho}$$

$$\vec{r} = (t^3 - 4t)\hat{i} + (t^2 + 4t)\hat{j} + (8t^2 - 3t^3)\hat{k}$$

$$\frac{d\vec{r}}{dt} = \dot{\vec{r}} = (3t^2 - 4)\hat{i} + (2t + 4)\hat{j} + (16t - 9t^2)\hat{k} = 8\hat{i} + 8\hat{j} - 4\hat{k}$$

$$\text{Now, } \frac{d\vec{r}}{dt} = \dot{\vec{r}} = \frac{d\vec{r}}{ds} \cdot \frac{ds}{dt} = v\hat{t}, \quad \text{Now, } v = |\dot{\vec{r}}| = \sqrt{8^2 + 8^2 + 4^2} = \sqrt{144} = 12.$$

$$\text{Again } v = \sqrt{(3t^2 - 4)^2 + (2t + 4)^2 + (16t - 9t^2)^2} = \sqrt{2(3t^2 - 4)^2 + 2(2t + 4)^2 + 2(16t - 9t^2)^2}$$

$$\therefore \frac{dv}{dt} = \frac{1}{2} \left[2(3t^2 - 4)^2 + 2(2t + 4)^2 + 2(16t - 9t^2)^2 \right]^{1/2}$$

$$= \frac{1}{2} \cdot \frac{1}{2} \cdot [2(3t^2 - 4)^2 + 2(2t + 4)^2 + 2(16t - 9t^2)^2]^{1/2} = \frac{1}{2} \cdot \frac{1}{2} \cdot (192 + 32 + 160) = \frac{1}{2} \cdot \frac{1}{2} \cdot 384 = 96$$

∴ Tangential component = 96 $\left[= \frac{dv}{dt} \right]$

$$\text{Now, } \kappa = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3}, \quad \text{Now, } \ddot{\vec{r}} = 6t\hat{i} + 2\hat{j} + (16 - 18t)\hat{k} = 12\hat{i} + 2\hat{j} - 2\hat{k}$$

$$= \frac{\sqrt{(152)^2 + (112)^2 + (80)^2}}{(12)^3}$$

$$\therefore \frac{v^2}{\rho} = \frac{v^2 \kappa}{1} = (12)^2 \times \frac{\sqrt{(152)^2 + (112)^2 + (80)^2}}{(12)^3} = \frac{1}{12} \times \sqrt{(38)^2 + (28)^2 + (20)^2} = \frac{1}{12} \times \sqrt{1936 + 784 + 400} = \frac{1}{12} \times \sqrt{3120} = \frac{1}{12} \times 4 \times 2 \times \sqrt{390} = \frac{1}{3} \times \sqrt{390}$$

Ex: Show that the radius of curvature of a plane curve $y = f(x), z = 0$ is given by $\rho = \frac{(1+y'^2)^{3/2}}{|y''|}$.
And the torsion $\tau = 0$ for this plane curve.

For a plane curve, i.e., a curve in the xy -plane

$$\vec{r} = x\hat{i} + y\hat{j}, \text{ where } y = f(x). \text{ Let } x = t, \quad y = f(t) \text{ then}$$

$$\dot{\vec{r}} = \dot{x}\hat{i} + \dot{y}\hat{j} = \hat{i} + \dot{y}\hat{j}$$

$$\ddot{\vec{r}} = \ddot{y}\hat{j}, \quad \ddot{\vec{r}} = \ddot{y}\hat{j}$$

$$\therefore K = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3} = \frac{|\dot{y}\hat{k}|}{(1+\dot{y}^2)^{3/2}} = \frac{|\dot{y}|}{(1+\dot{y}^2)^{3/2}}$$

Now, $\dot{y} = \frac{dy}{dt} = \frac{dy}{dx} \cdot \frac{dx}{dt} = y' \dot{x} = y' [\because \dot{x} = 1]$

$$\ddot{y} = \frac{d}{dt}(\dot{y}) = \frac{d}{dt}(y' \dot{x}) = \ddot{y} \dot{x}^2 + y' \ddot{x} = y'' [\because \ddot{x} = 0]$$

$$\therefore \rho = \frac{1}{K} = \frac{(1+y'^2)^{3/2}}{|y''|}$$

$$\tau = \frac{[\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}]}{|\dot{\vec{r}} \times \ddot{\vec{r}}|^2} = \frac{0}{\dot{y}^2} = 0$$

Ex: Prove that for the space curve $\vec{r} = \vec{r}(s)$, $\tau = \frac{\frac{d\vec{r}}{ds} \cdot \frac{d^2\vec{r}}{ds^2} \times \frac{d^3\vec{r}}{ds^3}}{(\frac{d^2\vec{r}}{ds^2})^2}$
where $\tau = \frac{[\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}]}{|\dot{\vec{r}} \times \ddot{\vec{r}}|^2}$ for the space curve $\vec{r} = \vec{r}(t)$.

Soln: $\dot{\vec{r}} = \frac{d\vec{r}}{dt} = \frac{d\vec{r}}{ds} \cdot \frac{ds}{dt} = \dot{s} \frac{d\vec{r}}{ds}$

$$\ddot{\vec{r}} = \frac{d^2\vec{r}}{dt^2} = \frac{d}{dt}(\dot{\vec{r}}) = \frac{d}{dt}(\dot{s} \frac{d\vec{r}}{ds}) = \ddot{s} \frac{d\vec{r}}{ds} + \dot{s}^2 \frac{d^2\vec{r}}{ds^2}$$

$$\ddot{\vec{r}} = \frac{d}{dt}(\ddot{\vec{r}}) = \frac{d}{dt}(\ddot{s} \frac{d\vec{r}}{ds} + \dot{s}^2 \frac{d^2\vec{r}}{ds^2}) = \ddot{s} \frac{d\vec{r}}{ds} + \ddot{s} \dot{s} \frac{d^2\vec{r}}{ds^2} + 2\dot{s} \ddot{s} \frac{d^2\vec{r}}{ds^2} + \dot{s}^3 \frac{d^3\vec{r}}{ds^3}$$

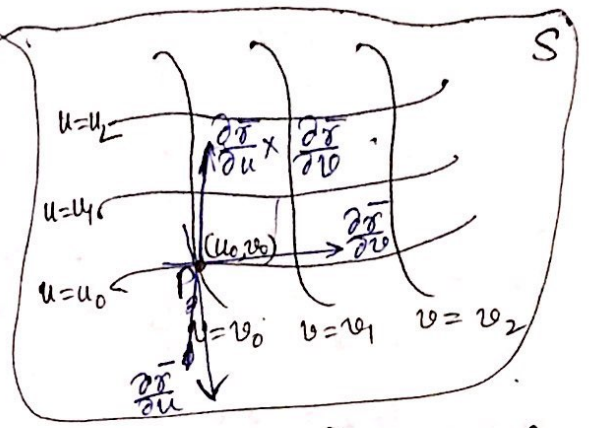
$$\dot{\vec{r}} \times \ddot{\vec{r}} = \dot{s} \dot{s} \frac{d\vec{r}}{ds} \times \frac{d\vec{r}}{ds} + \dot{s}^3 \frac{d\vec{r}}{ds} \times \frac{d^2\vec{r}}{ds^2} = \dot{s}^3 \frac{d\vec{r}}{ds} \times \frac{d^2\vec{r}}{ds^2}$$

$$[\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}] = \dot{s}^3 \ddot{s} \frac{d\vec{r}}{ds} \cdot \frac{d\vec{r}}{ds} \times \frac{d^2\vec{r}}{ds^2} + 3\dot{s}^4 \ddot{s} \frac{d^2\vec{r}}{ds^2} \cdot \frac{d\vec{r}}{ds} \times \frac{d^2\vec{r}}{ds^2} + \dot{s}^6 \frac{d^3\vec{r}}{ds^3} \cdot \frac{d\vec{r}}{ds} \times \frac{d^2\vec{r}}{ds^2}$$

$$\tau = \frac{[\dot{\vec{r}} \ddot{\vec{r}} \ddot{\vec{r}}]}{|\dot{\vec{r}} \times \ddot{\vec{r}}|^2} = \frac{\frac{d\vec{r}}{ds} \cdot \frac{d^2\vec{r}}{ds^2} \times \frac{d^3\vec{r}}{ds^3}}{(\frac{d^2\vec{r}}{ds^2})^2}$$

⑥ Show that the eqn $\vec{r} = \vec{r}(u, v)$ represents a surface.
 Show that $\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v}$ represents a vector normal to the surface.

① if u have a fixed value, say $u_0, u_1, u_2, \dots$ then $\vec{r} = \vec{r}(u_0, v)$, $\vec{r} = \vec{r}(u_1, v)$, $\vec{r} = \vec{r}(u_2, v), \dots$ represent curves denoted by respectively, $u = u_0, u = u_1, u = u_2, \dots$



As v varies, $\vec{r} = \vec{r}(u, v)$ represents a curve which moves in space and generates a surface.

Similarly $v = v_0, v = v_1, v = v_2, \dots$ represent curves on the surface.

(u, v) defines the curvilinear coordinates on the surface. $\frac{\partial \vec{r}}{\partial u}, \frac{\partial \vec{r}}{\partial v}$ at P represents a tangent vector to the surface $v = v_0$ & $u = u_0$ resp.

$\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} = \vec{n}$, the normal vector to the surface S at $P(u_0, v_0)$

Ex:- Find the eqns for the tangent plane and normal line to the surface $4z = x^2 - y^2$ at the point $(3, 1, 2)$

Soln: Let $x = u, y = v, z = \frac{u^2 - v^2}{4}$ be parametric eqns of the surface.

The p.v. to any point on the surface is

$\vec{r} = u\hat{i} + v\hat{j} + \frac{u^2 - v^2}{4}\hat{k}$

$\therefore \frac{\partial \vec{r}}{\partial u} = \hat{i} + \frac{u}{2}\hat{k}, \quad \frac{\partial \vec{r}}{\partial v} = \hat{j} - \frac{v}{2}\hat{k}$
 Now, $\left. \frac{\partial \vec{r}}{\partial u} \right|_{(3,1,2)} = \hat{i} + \frac{3}{2}\hat{k}, \quad \left. \frac{\partial \vec{r}}{\partial v} \right|_{(3,1,2)} = \hat{j} - \frac{1}{2}\hat{k}$

$\therefore \vec{n} = \left. \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right|_{(3,1,2)} = (\hat{i} + \frac{3}{2}\hat{k}) \times (\hat{j} - \frac{1}{2}\hat{k}) = \hat{k} + \frac{1}{2}\hat{j} - \frac{3}{2}\hat{i}$

$\vec{n}$ is the normal to the surface $(3, 1, 2)$

The p.v. to the point $(3, 1, 2)$ is $\vec{r}_0 = 3\hat{i} + \hat{j} + 2\hat{k}$

" " " any " on the tangent plane is $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

$\therefore (\vec{r} - \vec{r}_0) \cdot \vec{n} = 0 \Rightarrow (x-3)\hat{i} + (y-1)\hat{j} + (z-2)\hat{k} \cdot (\frac{3}{2}\hat{i} - \frac{1}{2}\hat{j} + \hat{k}) = 0$

$\Rightarrow -\frac{3}{2}(x-3) + \frac{1}{2}(y-1) + (z-2) = 0 \Rightarrow 3(x-3) - (y-1) - 2(z-2) = 0$

$\Rightarrow \boxed{3x - y - 2z = 4}$ $\rightarrow$ eqn of the tangent plane at $(3, 1, 2)$

Eqn of the normal line $\rightarrow (\vec{r} - \vec{r}_0) \times \vec{n} = \vec{0}, \quad x = 3t+3, y = 1-t, z = 2+t$

Frenet-Serret Formulae:

$$\frac{d\bar{T}}{ds} = \kappa \bar{N}, \quad \frac{d\bar{N}}{ds} = \tau \bar{B} - \kappa \bar{T}, \quad \frac{d\bar{B}}{ds} = -\tau \bar{N}$$

Osculating Plane to a curve at a point P is the plane containing the tangent and principal normal at P.
Normal Plane is the plane through P perpendicular to the tangent.

Rectifying Plane is the plane through P perpendicular to the principal normal.

~~Ex: Find~~

Ex: Find Eqs for the tangent, principal normal, binormal; and also the eqns for the osculating plane, normal plane and rectifying plane to the curve $x = 3t - t^3$, $y = 3t^2$, $z = 3t + t^3$ at the point where $t = 1$.

Soln: The p.v. is $\bar{r} = (3t - t^3)\bar{i} + 3t^2\bar{j} + (3t + t^3)\bar{k}$

$$\frac{d\bar{r}}{dt} = (3 - 3t^2)\bar{i} + 6t\bar{j} + (3 + 3t^2)\bar{k}$$

$$\frac{ds}{dt} = \left| \frac{d\bar{r}}{dt} \right| = \sqrt{(3-3t^2)^2 + (6t)^2 + (3+3t^2)^2} = \sqrt{18 + 18t^4 + 36t^2} = 3\sqrt{2}(1+t^2)$$

$$\bar{T} = \frac{d\bar{r}}{ds} = \frac{d\bar{r}/dt}{ds/dt} = \frac{(1-t^2)\bar{i} + 2t\bar{j} + (1+t^2)\bar{k}}{\sqrt{2}(1+t^2)}$$

$$\begin{aligned} \frac{d\bar{T}}{dt} &= \frac{\sqrt{2}(1+t^2) \cdot (-2t\bar{i} + 2\bar{j} + 2t\bar{k}) - 2\sqrt{2}t \{ (1-t^2)\bar{i} + 2t\bar{j} + (1+t^2)\bar{k} \}}{2(1+t^2)^2} \\ &= \frac{-4\sqrt{2}t\bar{i} + 2\sqrt{2}\bar{j}(1+t^2) - 2\sqrt{2}t\bar{i} + \sqrt{2}\bar{j}(1-t^2)}{2(1+t^2)^2} = \frac{-2t\bar{i} + \bar{j}(1-t^2)}{(1+t^2)^2} \end{aligned}$$

$$\frac{d\bar{T}}{ds} = \frac{d\bar{T}/dt}{ds/dt} = \frac{-2t\bar{i} + \bar{j}(1-t^2)}{3(1+t^2)^3} \cdot \frac{(1+t^2)}{3(1+t^2)^3} = \frac{1}{3(1+t^2)^2}$$

$$\frac{d\bar{T}}{ds} = \kappa \bar{N} \Rightarrow \kappa = \left| \frac{d\bar{T}}{ds} \right| = \frac{\sqrt{4t^2 + (1-t^2)^2}}{3(1+t^2)^3} = \frac{1}{3(1+t^2)^2}$$

$$\therefore \bar{N} = \frac{1}{\kappa} \frac{d\bar{T}}{ds} = \frac{-2t\bar{i} + \bar{j}(1-t^2)}{(1+t^2)^2}$$

$$\begin{aligned} \text{Then } \bar{B} &= \bar{T} \times \bar{N} = \frac{1}{\sqrt{2}(1+t^2)^2} \{ (1-t^2)\bar{i} + 2t\bar{j} + (1+t^2)\bar{k} \} \times \{ -2t\bar{i} + \bar{j}(1-t^2) \} \\ &= \frac{1}{\sqrt{2}(1+t^2)^2} \{ (1-t^2)^2\bar{k} + 2t^2\bar{k} - 2t(1+t^2)\bar{j} - (1-t^4)\bar{i} \} \\ &= \frac{1}{\sqrt{2}(1+t^2)^2} \{ (t^2+1)\bar{k} - 2t(1+t^2)\bar{j} - (1-t^4)\bar{i} \} \end{aligned}$$

$$\bar{T}_0 = \frac{\bar{j} + \bar{k}}{\sqrt{2}}, \quad \bar{N}_0 = -\bar{i}, \quad \bar{B}_0 = -\frac{\bar{j} + \bar{k}}{\sqrt{2}}$$

If $\vec{A}$ denotes a given vector while $\vec{r}_0$ & $\vec{r}$ are the p.v.s of the initial point and arbitrary point of A, then $\vec{r} - \vec{r}_0$ is $\parallel$ to $\vec{A}$, so the eqn. of A is $(\vec{r} - \vec{r}_0) \times \vec{A} = \vec{0}$

$$\left. \begin{aligned} \text{Eqn of tangent is } (\vec{r} - \vec{r}_0) \times \vec{T}_0 &= \vec{0} \\ \text{" " principal normal is } (\vec{r} - \vec{r}_0) \times \vec{N}_0 &= \vec{0} \\ \text{" " binormal is } (\vec{r} - \vec{r}_0) \times \vec{B}_0 &= \vec{0} \end{aligned} \right\} \begin{aligned} \vec{r} &= x\vec{i} + y\vec{j} + z\vec{k} \\ \vec{r}_0 &= 2\vec{i} + 3\vec{j} + 4\vec{k} \end{aligned}$$

$$\begin{aligned} \text{Eqn of the osculating plane} &= (\vec{r} - \vec{r}_0) \cdot \vec{B}_0 = 0 \\ \text{" , } [(x-2)\vec{i} + (y-3)\vec{j} + (z-4)\vec{k}] \cdot \frac{(-\vec{j} + \vec{k})}{\sqrt{2}} &= 0 \\ \text{" , } -y+3+z-4 &= 0 \quad \text{" , } y-z+1=0 \end{aligned}$$

$$\begin{aligned} \text{Eqn of the normal plane is } (\vec{r} - \vec{r}_0) \cdot \vec{T}_0 &= 0 \\ \text{" , } [(x-2)\vec{i} + (y-3)\vec{j} + (z-4)\vec{k}] \cdot \frac{(\vec{i} + \vec{k})}{\sqrt{2}} &= 0 \\ \text{" , } x-2+z-4 &= 0 \quad \text{" , } x+z-6=0 \end{aligned}$$

$$\begin{aligned} \text{Eqn of the rectifying plane is } (\vec{r} - \vec{r}_0) \cdot \vec{N}_0 &= 0 \\ \text{" , } (x-2) \cdot (-1) &= 0 \quad \text{" , } \underline{x=2} \end{aligned}$$

Mechanics:

Problem: Show that the acceleration $\vec{a}$ of a particle which travels along a space curve with velocity $\vec{v}$ given by $\vec{a} = \frac{dv}{dt} \vec{T} + \frac{v^2}{\rho} \vec{N}$,

$$\begin{aligned} \vec{v} &= v \vec{T} \\ \vec{a} = \frac{d\vec{v}}{dt} &= \frac{dv}{dt} \vec{T} + v \frac{d\vec{T}}{dt} = \frac{dv}{dt} \vec{T} + \frac{ds}{dt} \frac{d\vec{T}}{ds} \frac{ds}{dt} = \frac{dv}{dt} \vec{T} + \frac{v^2}{\rho} \vec{N} \end{aligned}$$

$$\vec{T} = \frac{\frac{ds}{dt}}{\sqrt{(3t^2-4)^2 + (2t+4)^2 + (16t-9t^2)^2}} \left[(3t^2-4)\vec{i} + (2t+4)\vec{j} + (16t-9t^2)\vec{k} \right]$$

$$\frac{d\vec{T}}{dt} \frac{ds}{dt} = \frac{d}{dt} \left[(3t^2-4)\vec{i} + (2t+4)\vec{j} + (16t-9t^2)\vec{k} \right] \cdot \frac{ds}{dt}$$

$$\frac{d\vec{T}}{dt} \frac{ds}{dt} + \vec{T} \frac{d^2s}{dt^2} = 6t\vec{i} + 2\vec{j} + (16-18t)\vec{k}$$

$$12 \frac{d\vec{T}}{dt} + \vec{T} \sqrt{144+4+400} = 12\vec{i} + 2\vec{j} - 20\vec{k}$$

$$\therefore 12 \frac{d\vec{T}}{dt} + \frac{2\vec{i} + 2\vec{j} - \vec{k}}{3} \sqrt{548} = 12\vec{i} + 2\vec{j} - 20\vec{k}$$

$$\frac{1}{\rho} = K = \left| \frac{d\vec{T}}{ds} \right|$$

Ex. Find the unit normal to the surface

$$\vec{r} = a \cos u \sin v \hat{i} + a \sin u \sin v \hat{j} + a \cos v \hat{k} \quad (a > 0)$$

How? $\left\{ \begin{aligned} \left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| &= \sqrt{a^4 \sin^2 v} = a^2 \sin v, \text{ if } \sin v > 0 \\ &= -a^2 \sin v, \text{ if } \sin v < 0. \end{aligned} \right.$

$$\hat{n} = \pm \{ (\cos u \sin v) \hat{i} + (\sin u \sin v) \hat{j} + \cos v \hat{k} \}.$$

$$\frac{\partial \vec{r}}{\partial u} = -a \sin u \sin v \hat{i} + a \cos u \sin v \hat{j}$$

$$\frac{\partial \vec{r}}{\partial v} = a \cos u \cos v \hat{i} + a \sin u \cos v \hat{j} - a \sin v \hat{k}$$

Then $\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -a \sin u \sin v & a \cos u \sin v & 0 \\ a \cos u \cos v & a \sin u \cos v & -a \sin v \end{vmatrix}$

$$= -a^2 \cos u \sin^2 v \hat{i} - a^2 \sin u \sin^2 v \hat{j} - a^2 \sin v \cos v \hat{k}$$

represents a vector normal to the surface at any point (u, v) .

$$\text{Unit normal } \hat{n} = \frac{\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v}}{\left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right|}$$

Now $\left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| = \sqrt{a^4 \cos^2 u \sin^4 v + a^4 \sin^2 u \sin^4 v + a^4 \sin^2 v \cos^2 v}$

$$= \sqrt{a^4 \sin^2 v (\sin^2 v + \cos^2 v)} = \begin{cases} a^2 \sin v, & \text{if } \sin v > 0 \\ -a^2 \sin v, & \text{if } \sin v < 0. \end{cases}$$

$$\therefore \hat{n} = \frac{\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v}}{\left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right|} = \pm (\cos u \sin v \hat{i} + \sin u \sin v \hat{j} + \cos v \hat{k})$$